

Knowledge Base Creation by Reliability of Coordinates Detected from Videos for Finger Character Recognition

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- Background
- Purpose
- Proposed method
- Experiment and Evaluation
- Conclusion

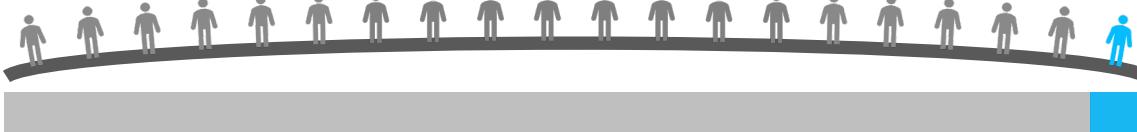
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Background



Social

A sign language translation system is very significant.



About 5% of the world population has hearing loss

Academic



Not enough datasets



Using special device for data extraction is costly



MLDL require a huge amount of image datasets and high computational cost

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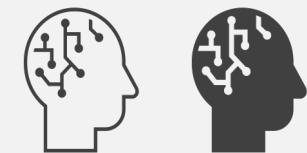
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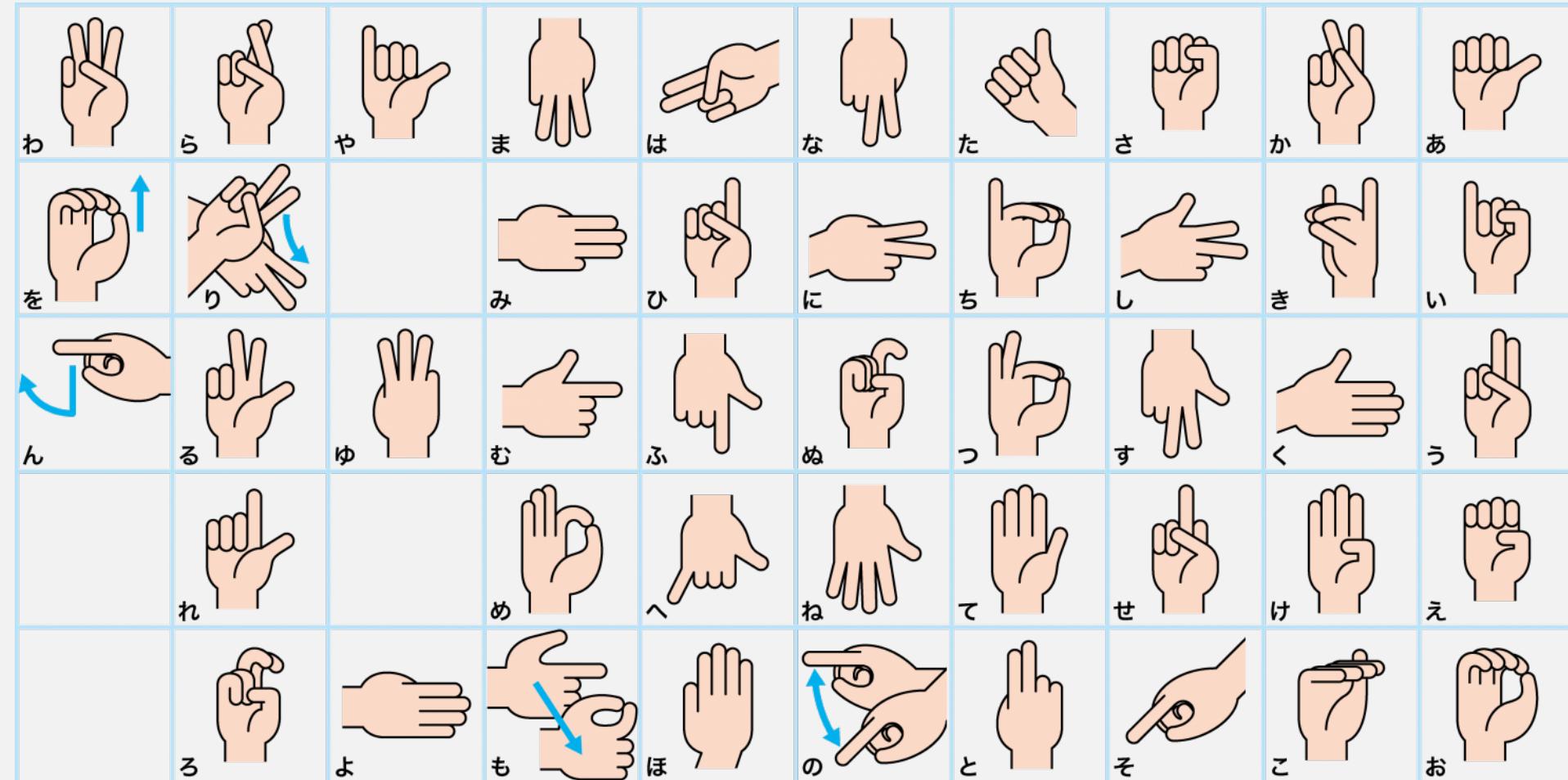


MLDL require a huge amount of image datasets and high computational cost

Japanese finger character



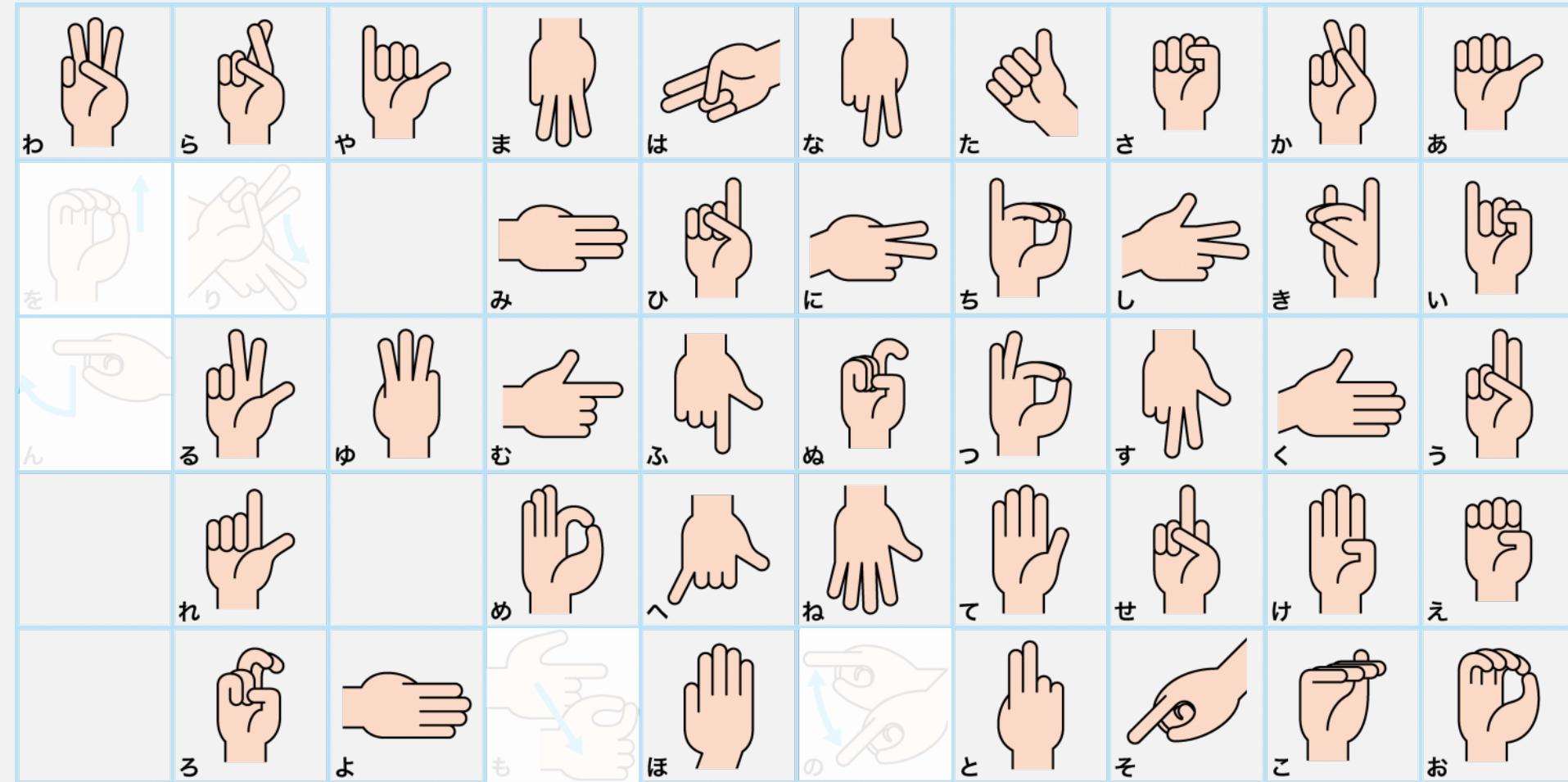
Background



Japanese finger character



Background



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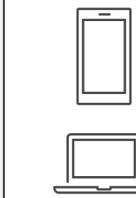
Main purpose

purpose

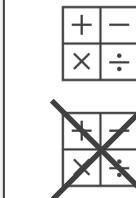
To construct a finger character recognition system



with a small image data set



to use a generic device



with low computational cost

Purpose of this work



We propose new knowledge base creation methods using the reliability of the finger joint coordinates.



We evaluate the knowledge base creation method.

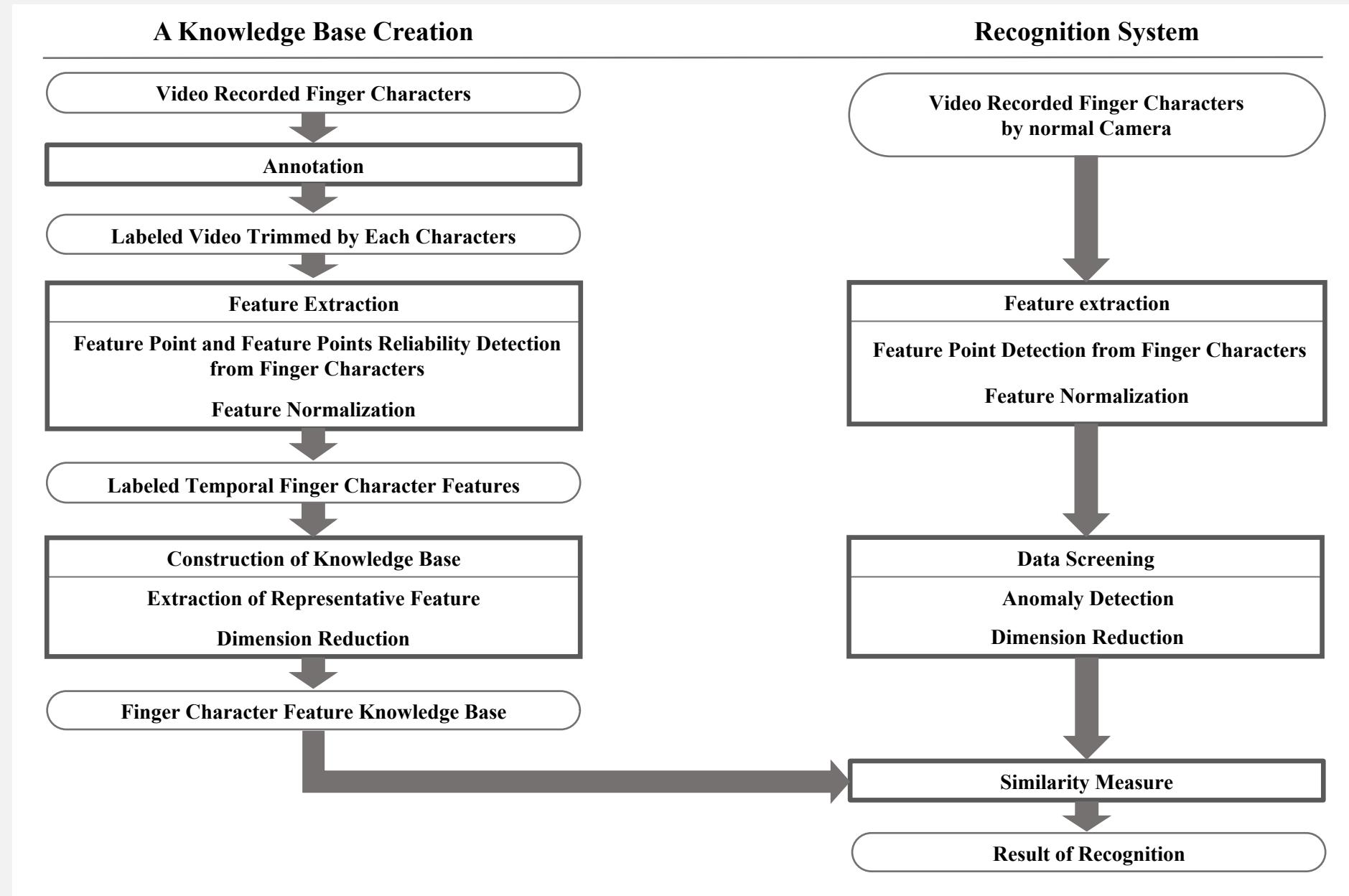


We implement a finger character recognition system with higher recognition accuracy.

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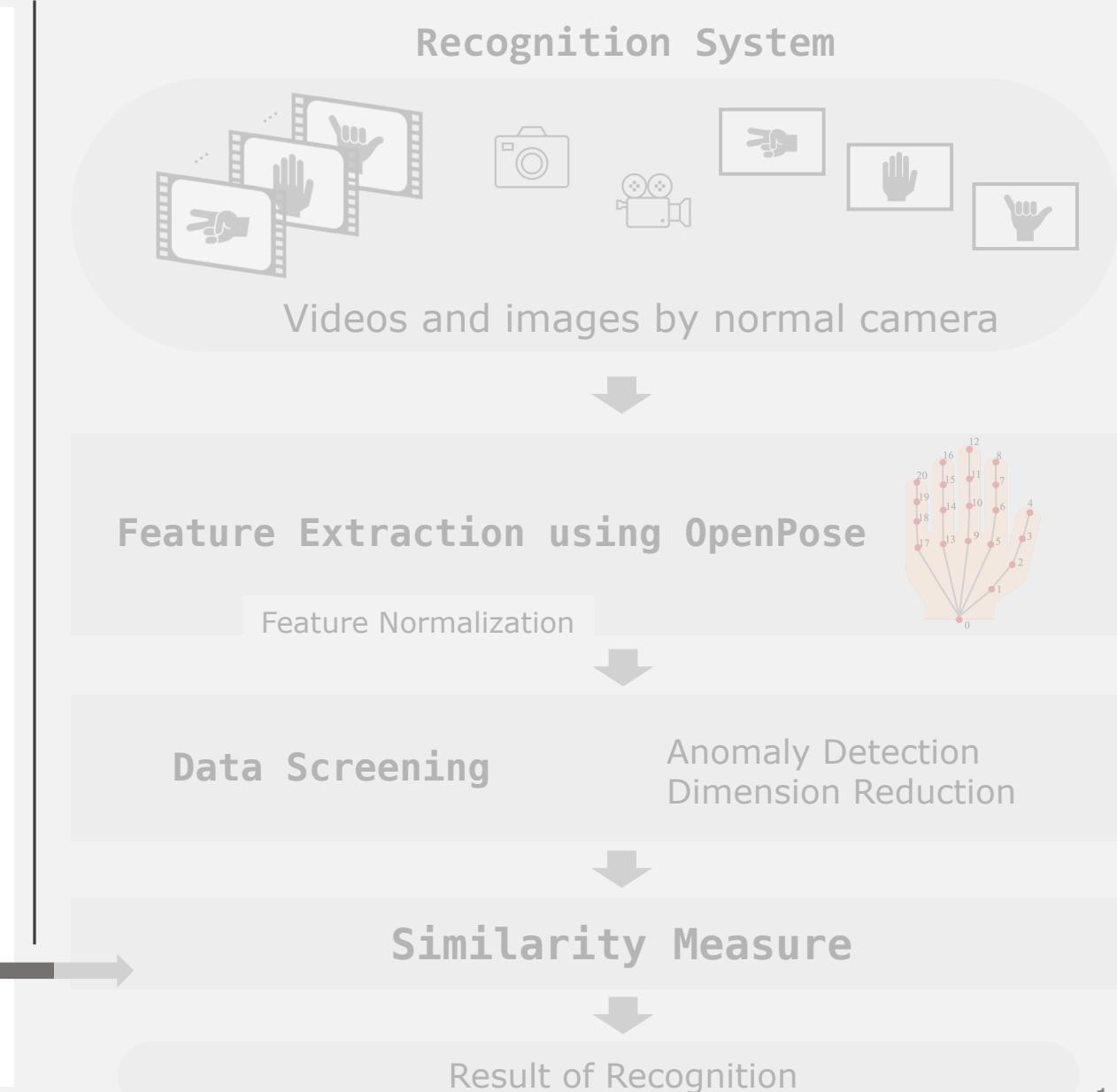
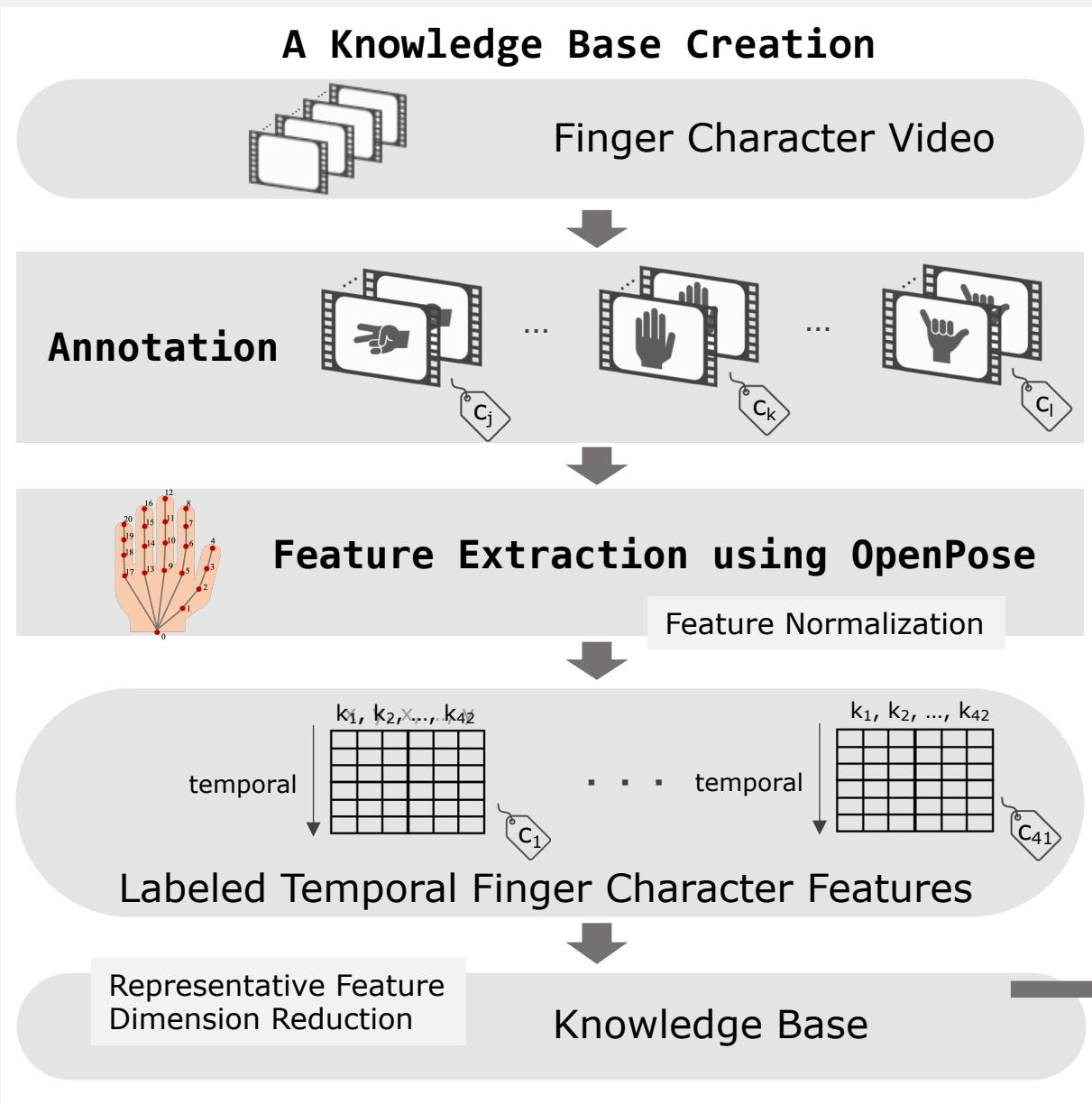
Overview of our recognition system

Proposed method

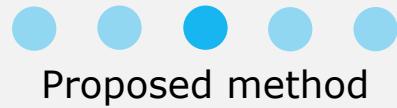


A knowledge base creation system

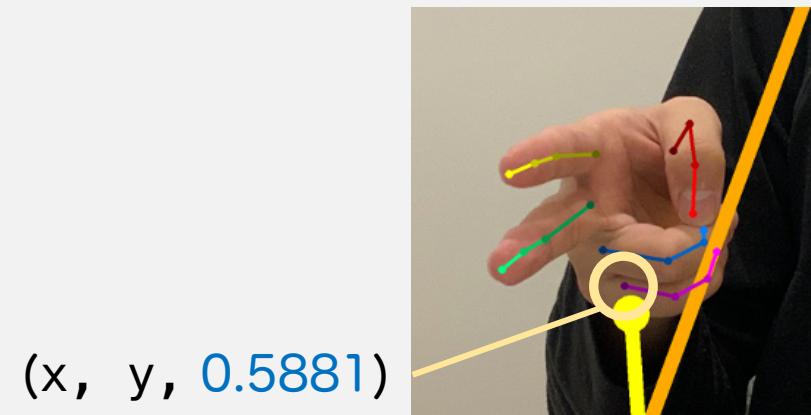
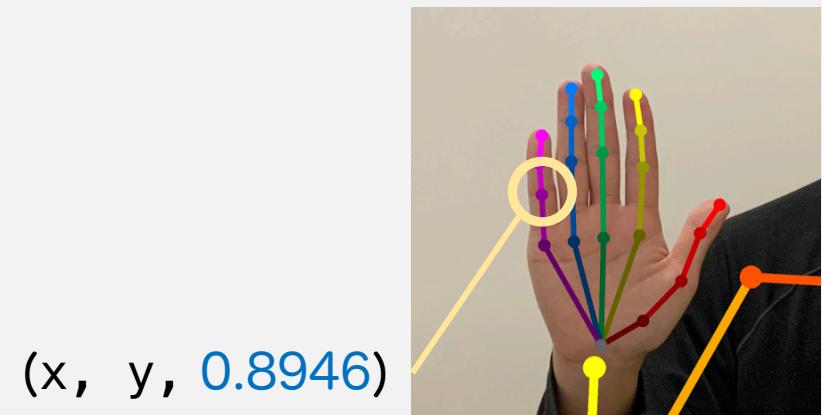
Proposed method



Definition of the reliability of coordinates



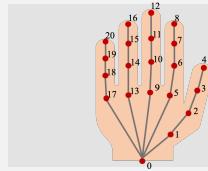
The reliability is a value in the range 0~1 that shows accuracy of the coordinates obtained by OpenPose.



(X-coordinate, Y-coordinate, the reliability of the coordinates)

Improvement point

Proposed method



Feature Extraction using OpenPose

↓ Finger joint coordinates

↓ the reliability of coordinates

	k_1x	k_1y	$k_{21}y$
t_1					
t_2					
:					
t_n					

*Labeled
Temporal Finger
Character Features
Matrix C*

	k_1r	k_2r	...	\ddots	$k_{21}r$
t_1					
t_2					
:					
t_n					

Matrix Γ

Labeled Temporal Finger Character Features

New Knowledge Base Creation Methods

new knowledge base creation methods by reliability of coordinates

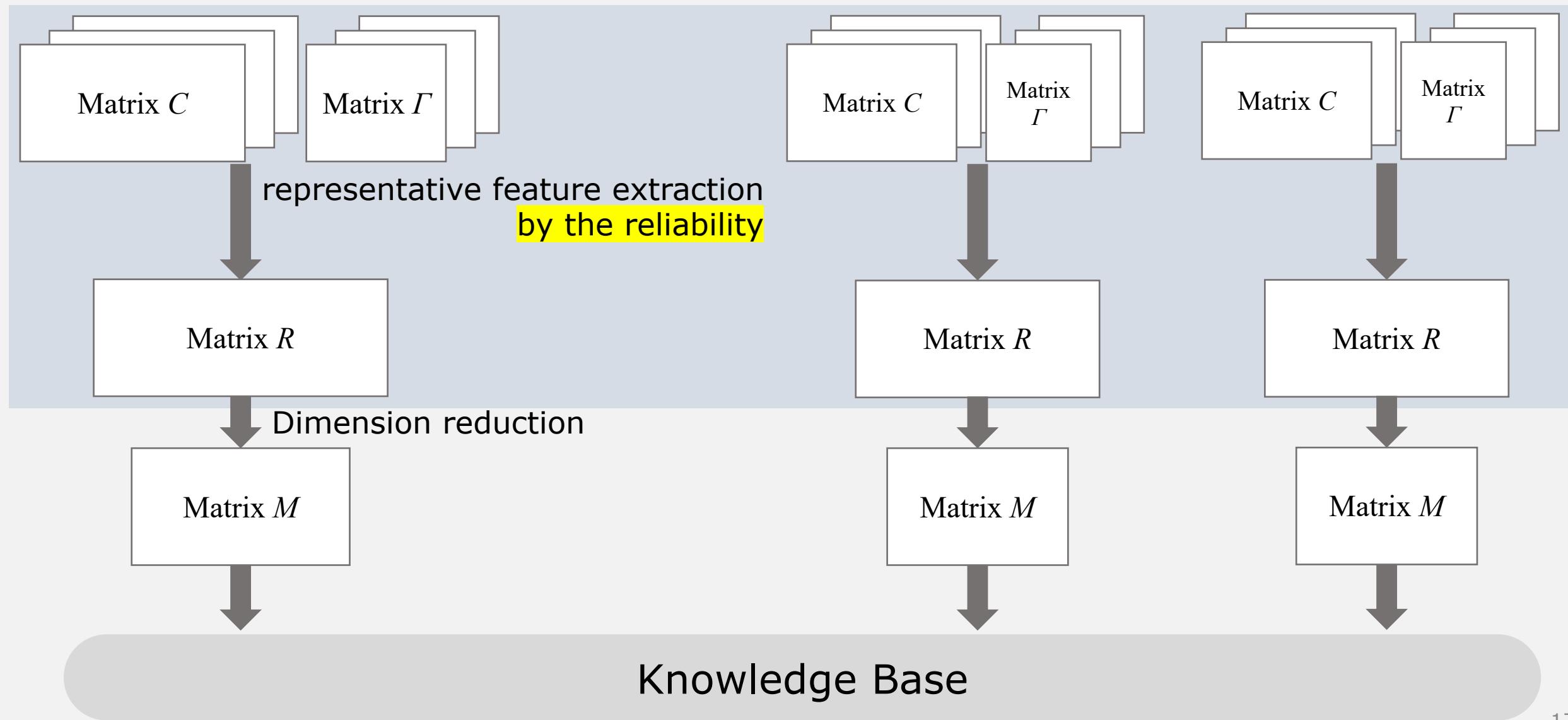


Knowledge Base

* $k_i x$: The coordinate of X $k_j y$: The coordinate of Y $k_l r$: The reliability of the coordinates (details in next slide)

Outline of new knowledge base creation methods by reliability

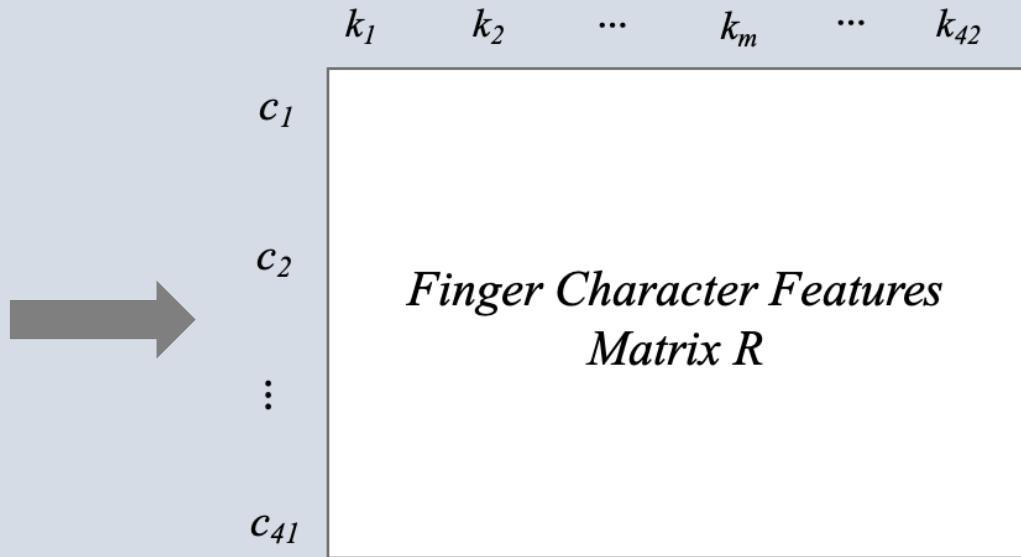
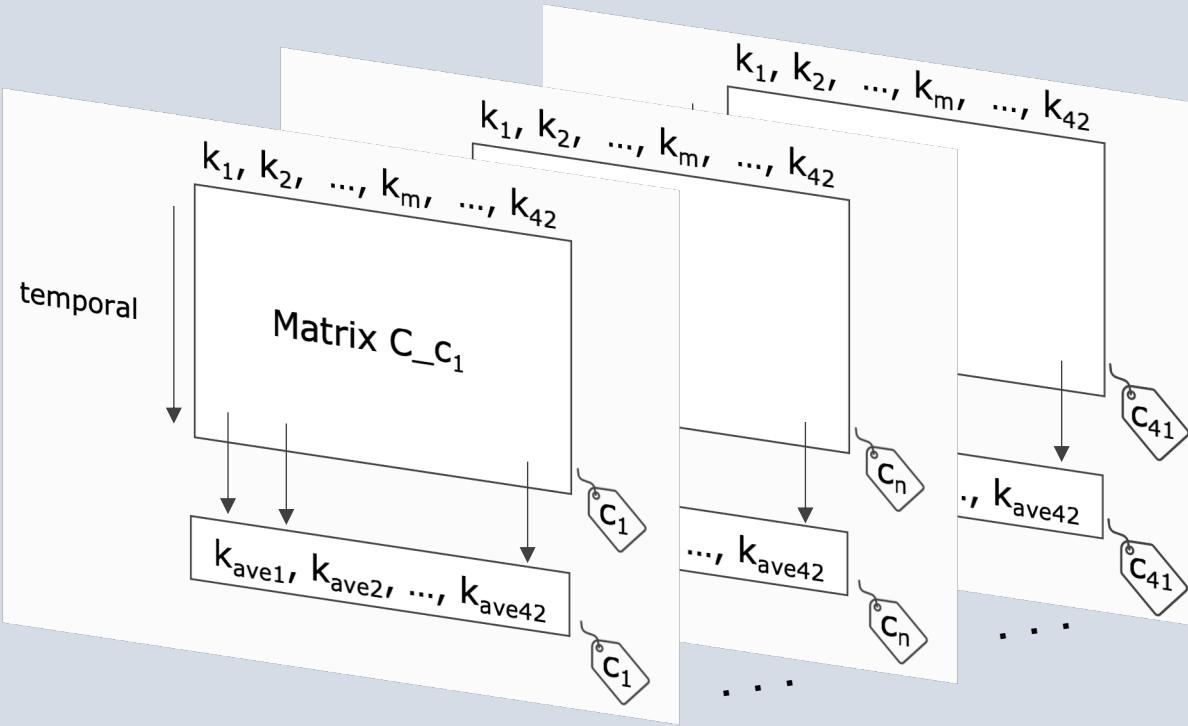
● ● ● ●
Proposed method



Representative feature extraction

Proposed method

Labeled Temporal Finger Character Features



k_{1-42} : X and Y coordinates for each of the 21 finger joint coordinates
 c_{1-n} : Each finger character

Representative feature extraction



- 1 Creation by **the highest average value**
- 2 Creation by **the highest minimum value**
- 3 Creation by **the average of averages**
- 4 Creation by **the sum of the maximum and minimum values**

① Creation by the highest average value

Proposed method

For each frame, calculate the average of the reliability.

Find the highest average value.

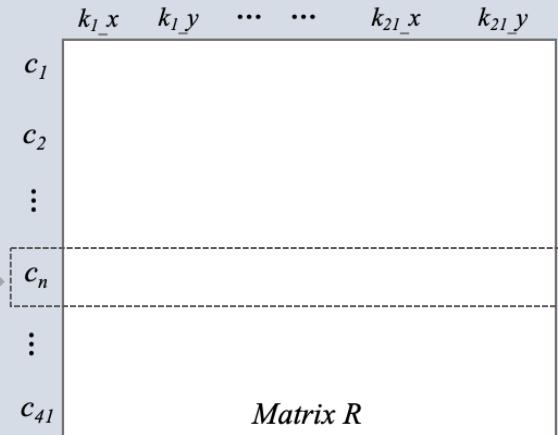
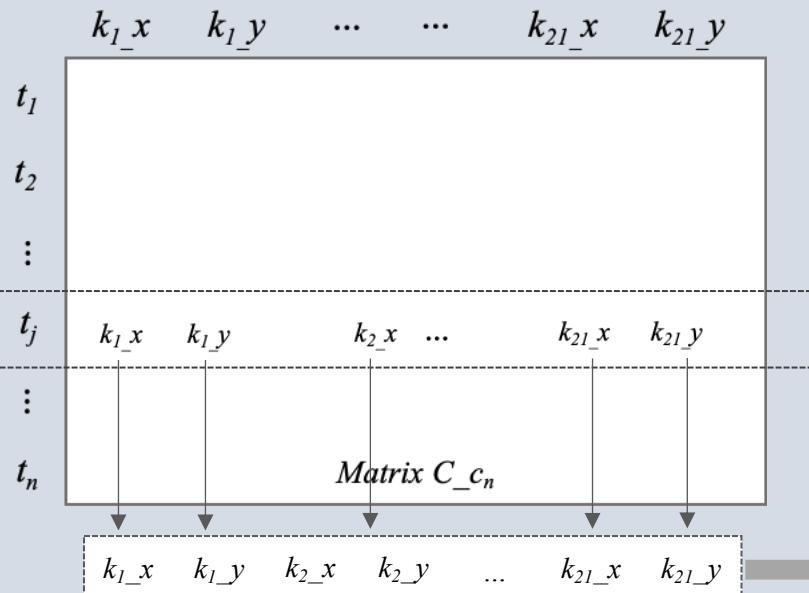
	$k_1.r$	$k_2.r$...	$k_{2I}.r$	
t_1					$t_1.ave$
t_2					$t_2.ave$
:					:
t_j					$t_j.ave$
⋮					⋮
t_n					$t_n.ave$



Extract the coordinates of the frame with the highest average.



Store the extracted representative values in the knowledge base



② Creation by the highest minimum value

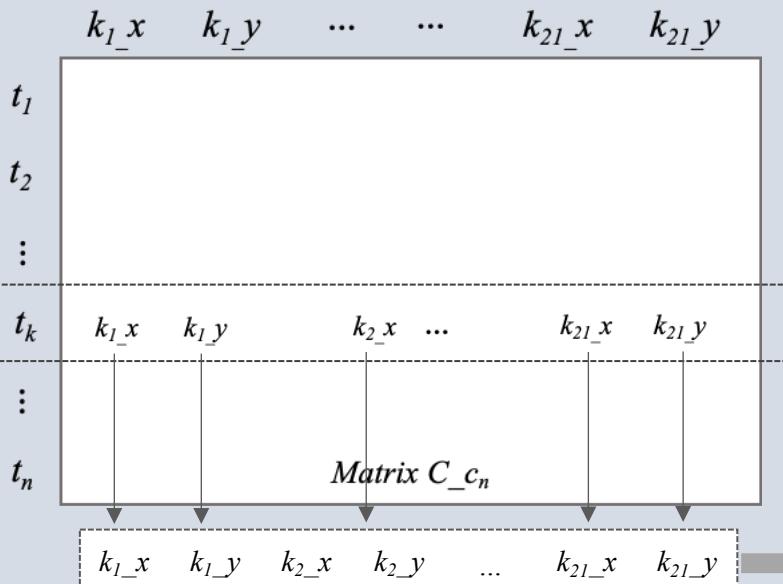
Proposed method

For each frame, extract the minimum value of the reliability.

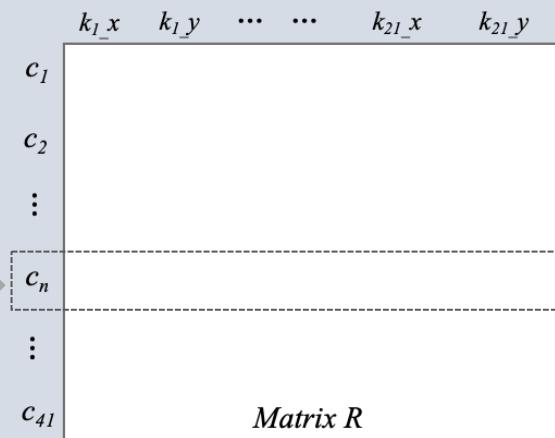
Find the highest minimum value.

	k_1_r	k_2_r	...	k_{2l_r}	
t_1					$t_1 \text{ min}$
t_2					$t_2 \text{ min}$
\vdots					\vdots
t_k	$Matrix \Gamma_{c_n}$				$t_k \text{ min}$ max
\vdots					\vdots
t_n					$t_n \text{ min}$

Extract the coordinates of the frame with the highest minimum value.



Store the extracted representative values in the knowledge base



③ Creation by the average of averages

Proposed method

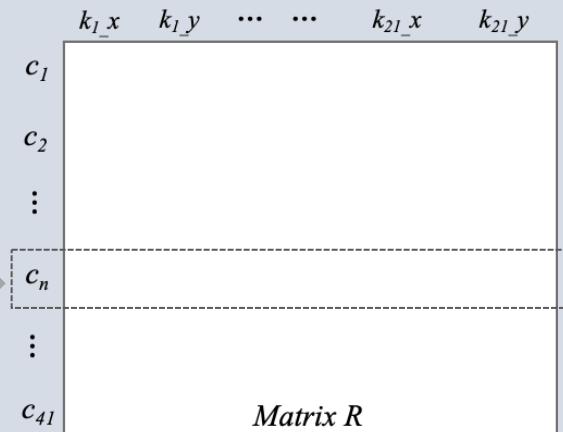
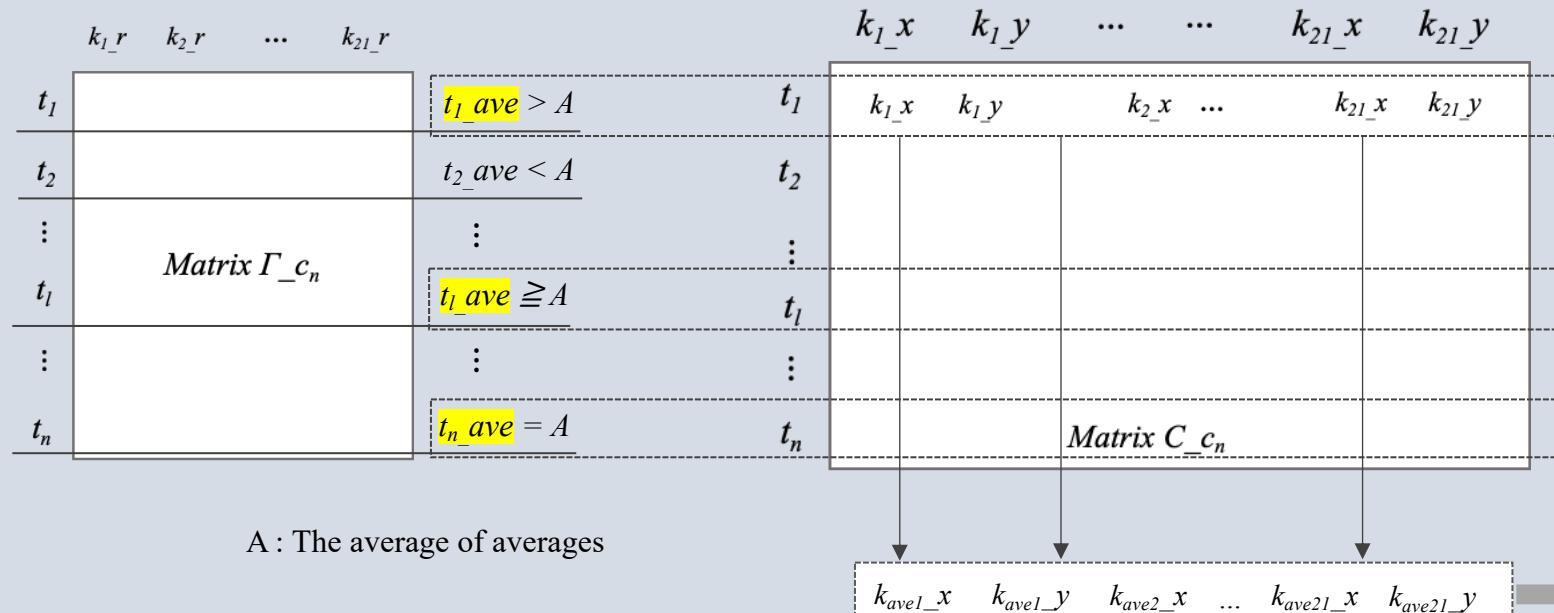
For each frame, calculate the average of the reliability.

Calculate the average value of all averages (= A)

Find all averages higher than A.

Calculate the average for the same coordinates of all extracted frames.

Store the extracted representative values in the knowledge base



④ Creation by the sum of the maximum and minimum values

Proposed method

For each frame, extract the maximum and minimum values of the reliability.

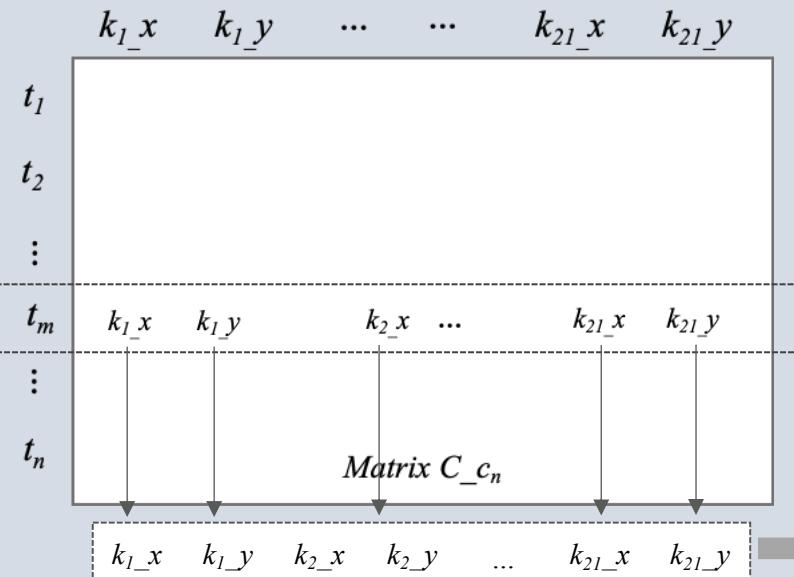
Sum the maximum and minimum values.

Extract the coordinates of the extracted frame.

Store the extracted representative values in the knowledge base

Find the highest value of the sum.

	$k_1.r$	$k_2.r$...	$k_{2l}.r$	
t_1					$t_1 \text{ max} + t_1 \text{ min}$
t_2					$t_2 \text{ max} + t_2 \text{ min}$
\vdots					\vdots
t_m	<i>Matrix Γ_c_n</i>		$t_m \text{ max} + t_m \text{ min}$	max	
\vdots			\vdots		
t_n					$t_n \text{ max} + t_n \text{ min}$

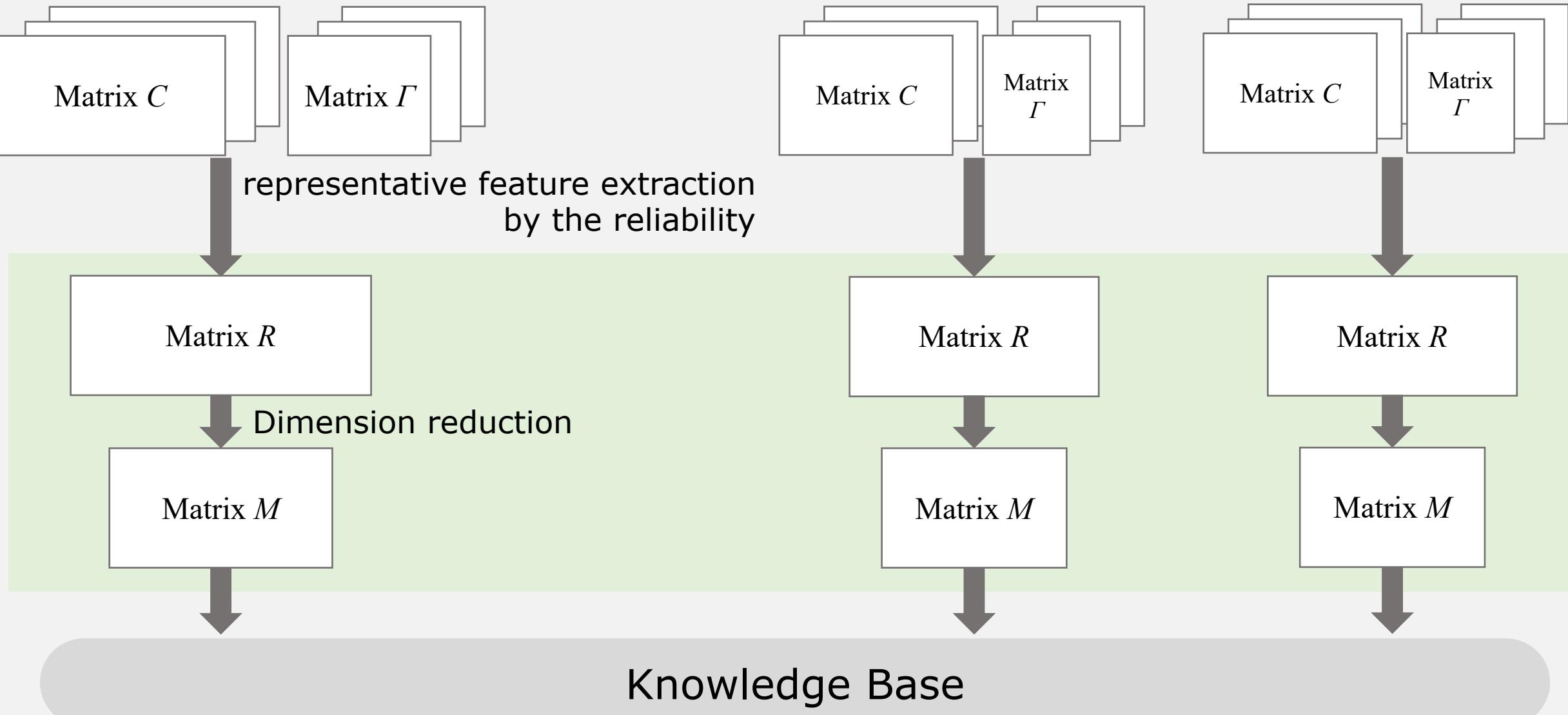


	$k_1.x$	$k_1.y$...	$k_{2l}.x$	$k_{2l}.y$
c_1					
c_2					
\vdots					
c_n					

Matrix R

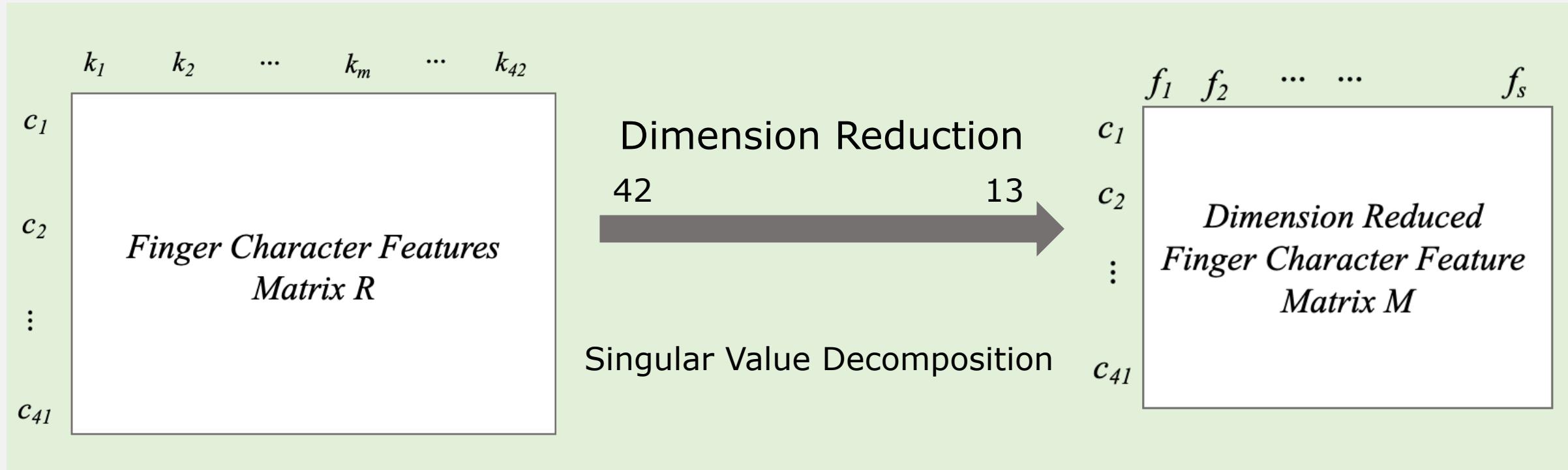
Outline of new knowledge base creation methods by reliability

● ● ● ●
Proposed method



Dimension reduction

Proposed method



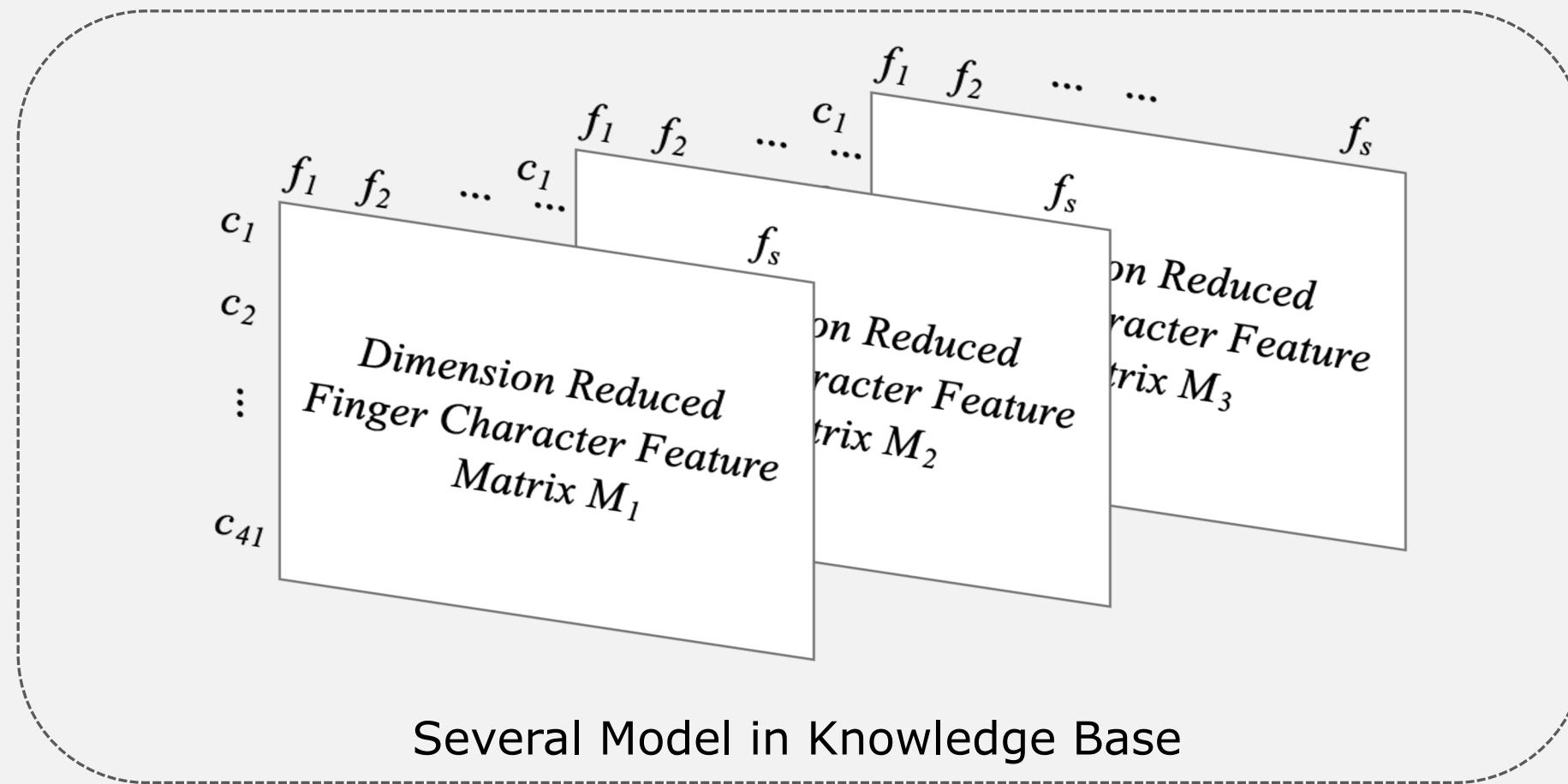
k_{1-42} : X and Y coordinates for each of the 21 finger joint coordinates

c_{1-n} : Each finger character

f_{1-s} : The dimension reduced finger character features

The knowledge base

Proposed method

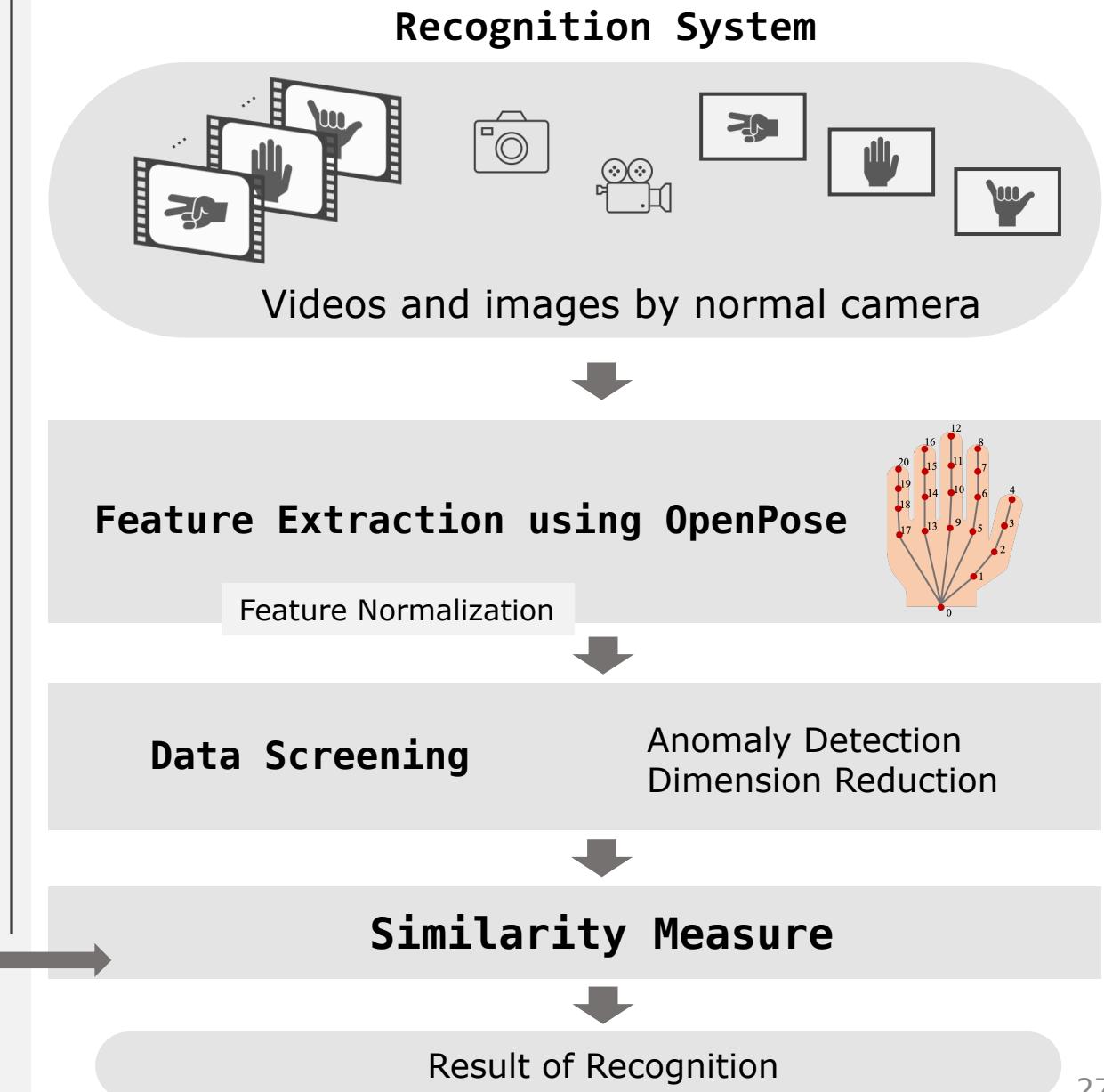
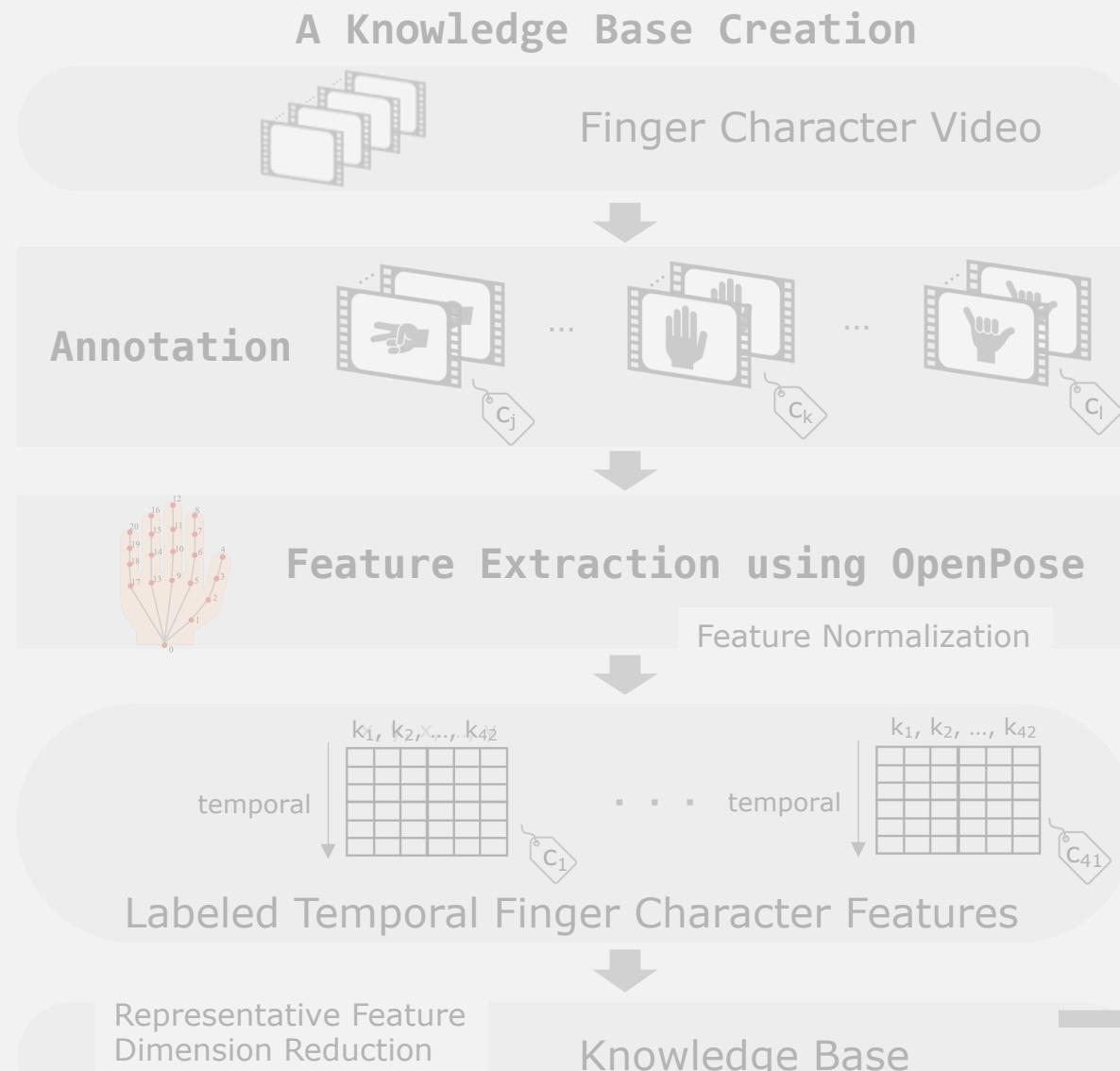


c_{1-n} : Each finger character

f_{1-s} : The dimension reduced finger character features

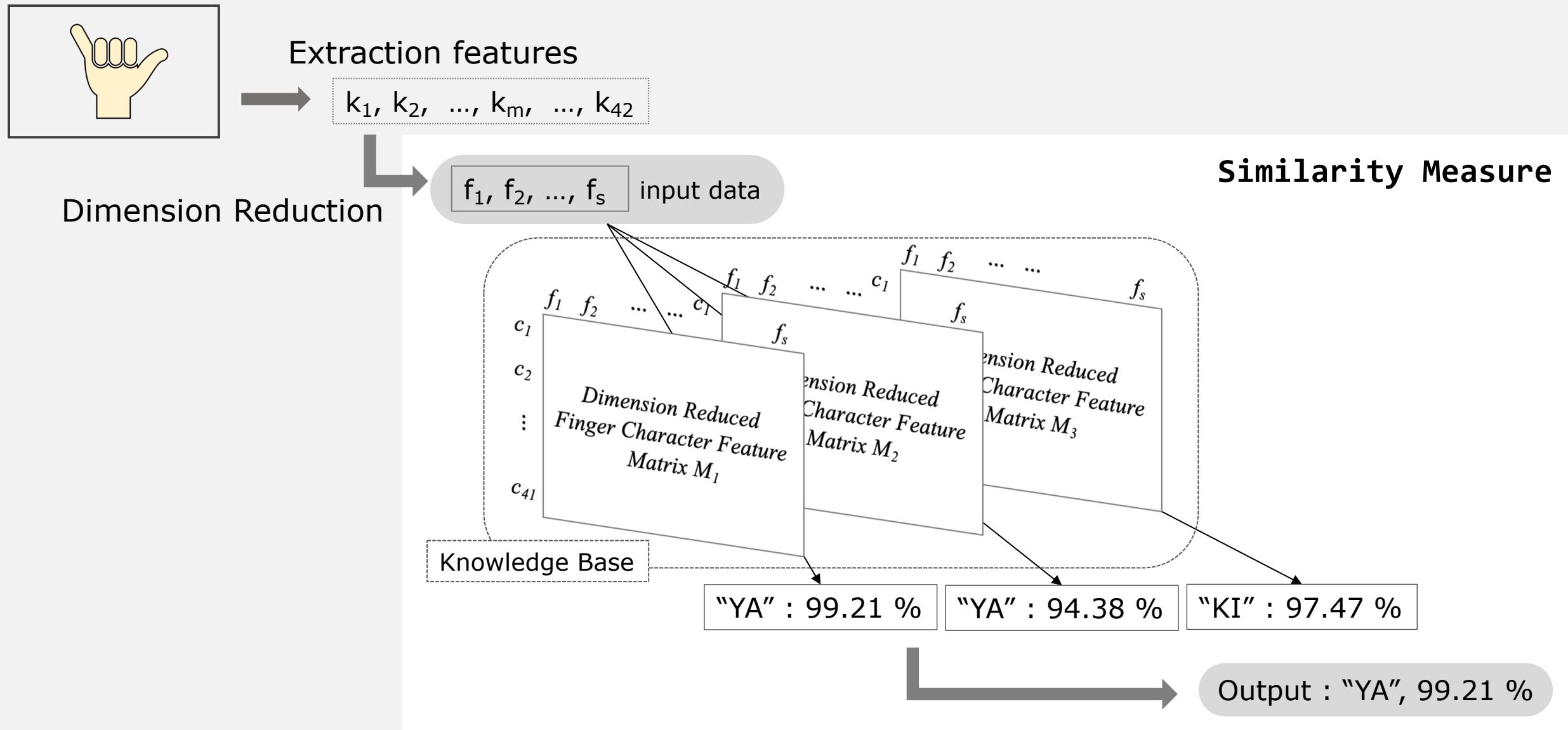
Recognition system

Proposed method



Similarity measure

Proposed method



k_{1-42} : X and Y coordinates for each of the 21 finger joint coordinates

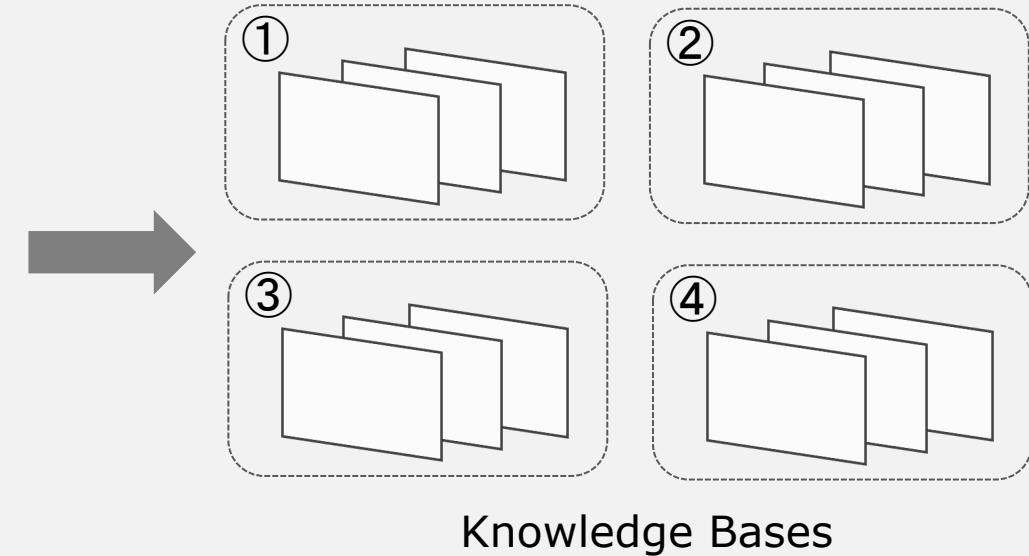
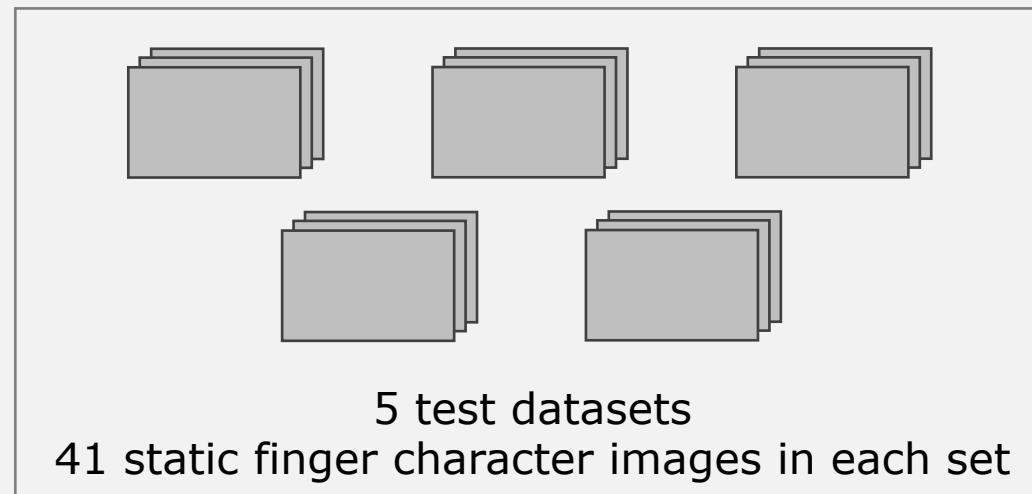
f_{1-s} : The dimension reduced finger character features

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Experiment

Verify accuracy using test data and knowledge base.



Evaluation

Evaluate and compare with recognition accuracy of previous work.

Experiment result



Perform recognition on each knowledge base and each of the five test data sets. Calculate the accuracy for each test data set.

Types of Knowledge base	Person-1	Person-2	Person-3	Person-4	Person-5	average
① Highest-Ave	87.50 %	63.41 %	60.98 %	68.75 %	62.50 %	68.63 %
② Highest-Min	82.50 %	63.41 %	60.98 %	65.63 %	62.50 %	67.00 %
③ Average-Ave	85.00 %	68.29 %	58.54 %	71.86 %	60.00 %	68.74 %
④ Sum-of-Max-Min	82.50 %	63.41 %	58.54 %	68.75 %	60.00 %	66.64 %

previous work	Person-1	Person-2	Person-3	Person-4	Person-5	average
accuracy	87.50 %	63.41 %	60.98 %	75.00 %	62.50 %	69.88 %

Person-n : The data consists 41 static finger characters in each set.

Results of our previous work and the results of the third approach (Average-Ave) that had the highest accuracy in this work.

	Person-1	Person-2	Person-3	Person-4	Person-5	Average
Previous work	87.50 %	63.41 %	60.98 %	75.00 %	62.50 %	69.88 %
③ Average-Ave	85.00 %	68.29 %	58.54 %	71.86 %	60.00 %	68.74 %

About 5%
Positive case

About 3%
Negative case

Example of positive cases



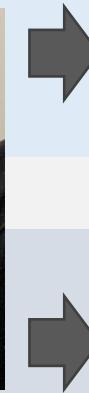
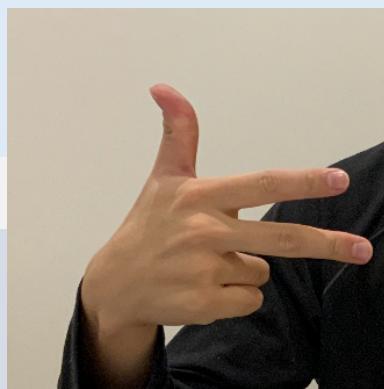
Experiment and Evaluation



③ Average-Ave



E

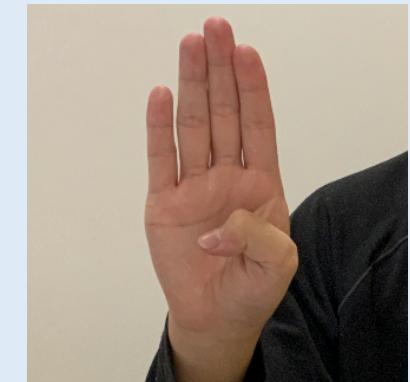


③ Average-Ave



SHI

previous work



KE

previous work

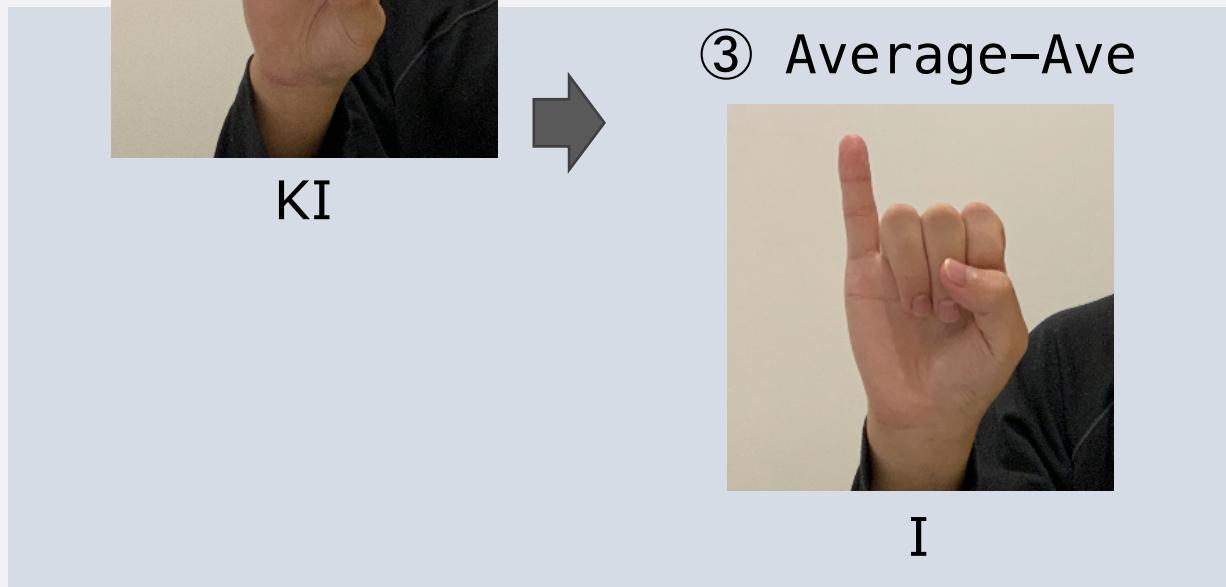
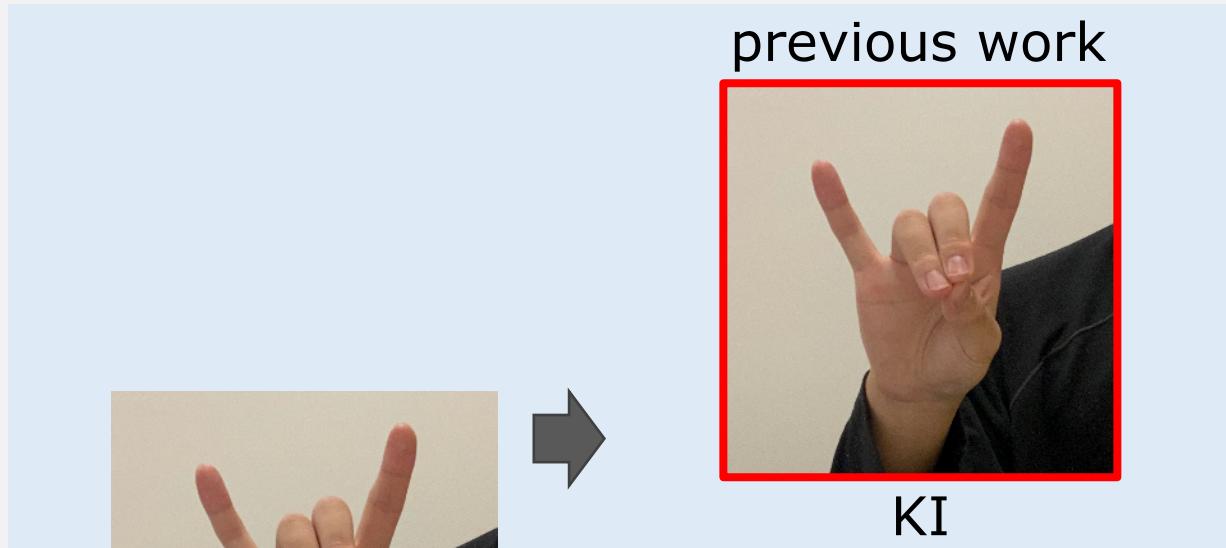


MU

Example of a negative case



Experiment and Evaluation



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We proposed a new knowledge base creation method using the reliability of coordinates detected from finger character videos for recognition.



Our method enables the creation of a knowledge base and metadata with high accuracy from a small amount of training data.



Our method achieves the same level of accuracy when comparing to our previous work in the finger character recognition using the knowledge base created in our method.

I

To improve the accuracy of the recognition

II

To develop the recognition of dynamic finger characters and sign language that has various motions

III

To develop an application