

# Knowledge Base Creation by Reliability of Coordinates Detected from Videos for Finger Character Recognition

Shinpei Hagimoto<sup>\*</sup>, Takuma Nitta<sup>\*</sup>, Ari Yanase<sup>\*</sup>,  
Takafumi Nakanishi<sup>\*</sup>, Ryotaro Okada<sup>\*</sup>, Virach Sornlertlamvanich<sup>\*</sup>  
Department of Data Science Musashino University<sup>\*</sup>

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# Outline



- Background
- Purpose
- Proposed method
- Experiment and Evaluation
- Conclusion



# Outline



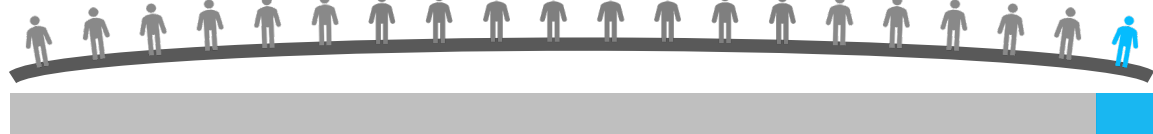
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# Background

## Social

A sign language translation system is very significant.



About 5% of the world population has hearing loss

## Academic



Not enough datasets



Using special device for data extraction is costly



MLDL require a huge amount of image datasets and high computational cost



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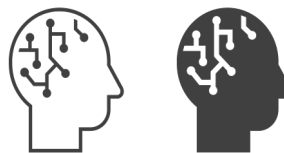
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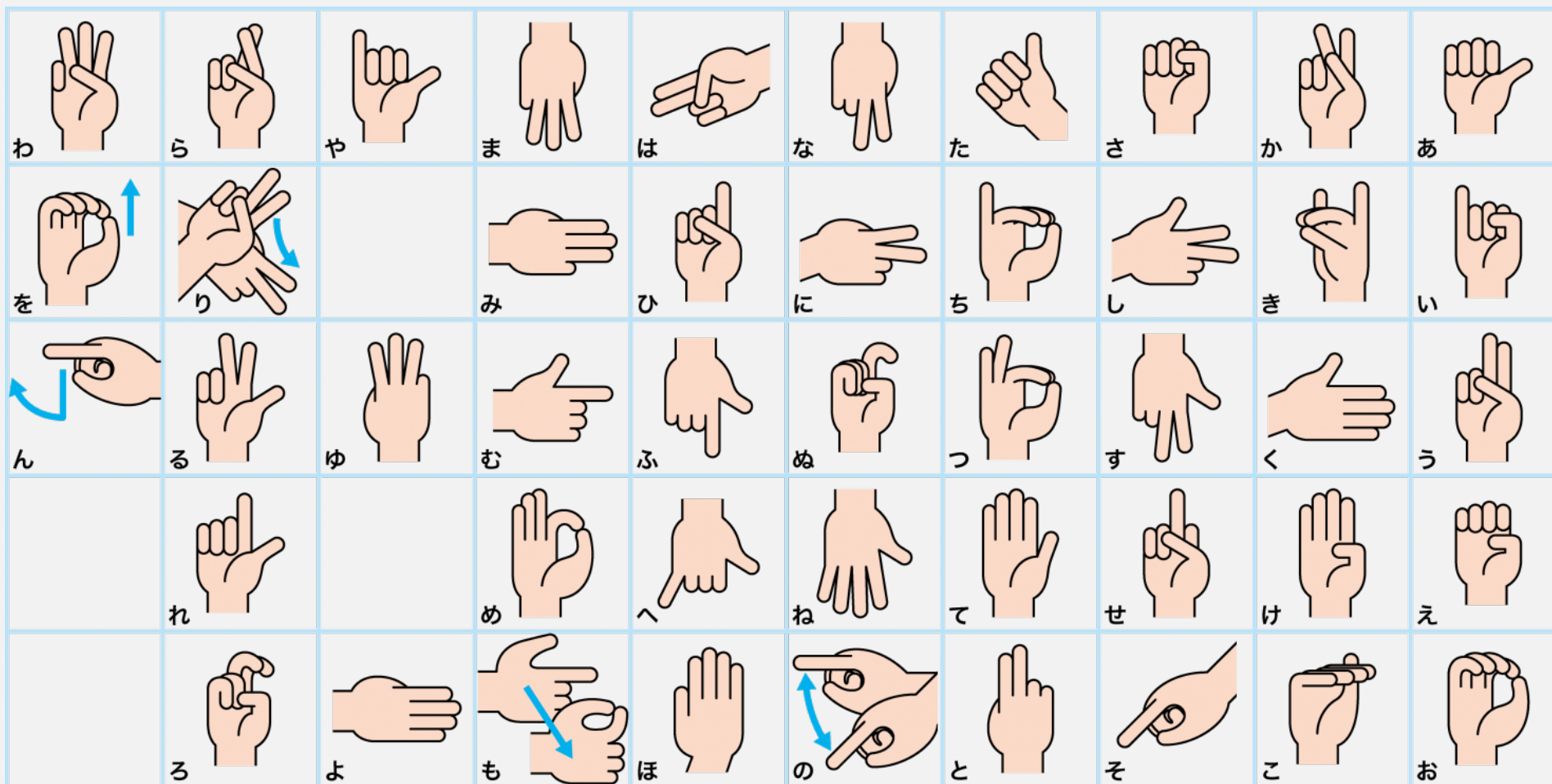


MLDL require a huge amount of image datasets and high computational cost



# Japanese finger character

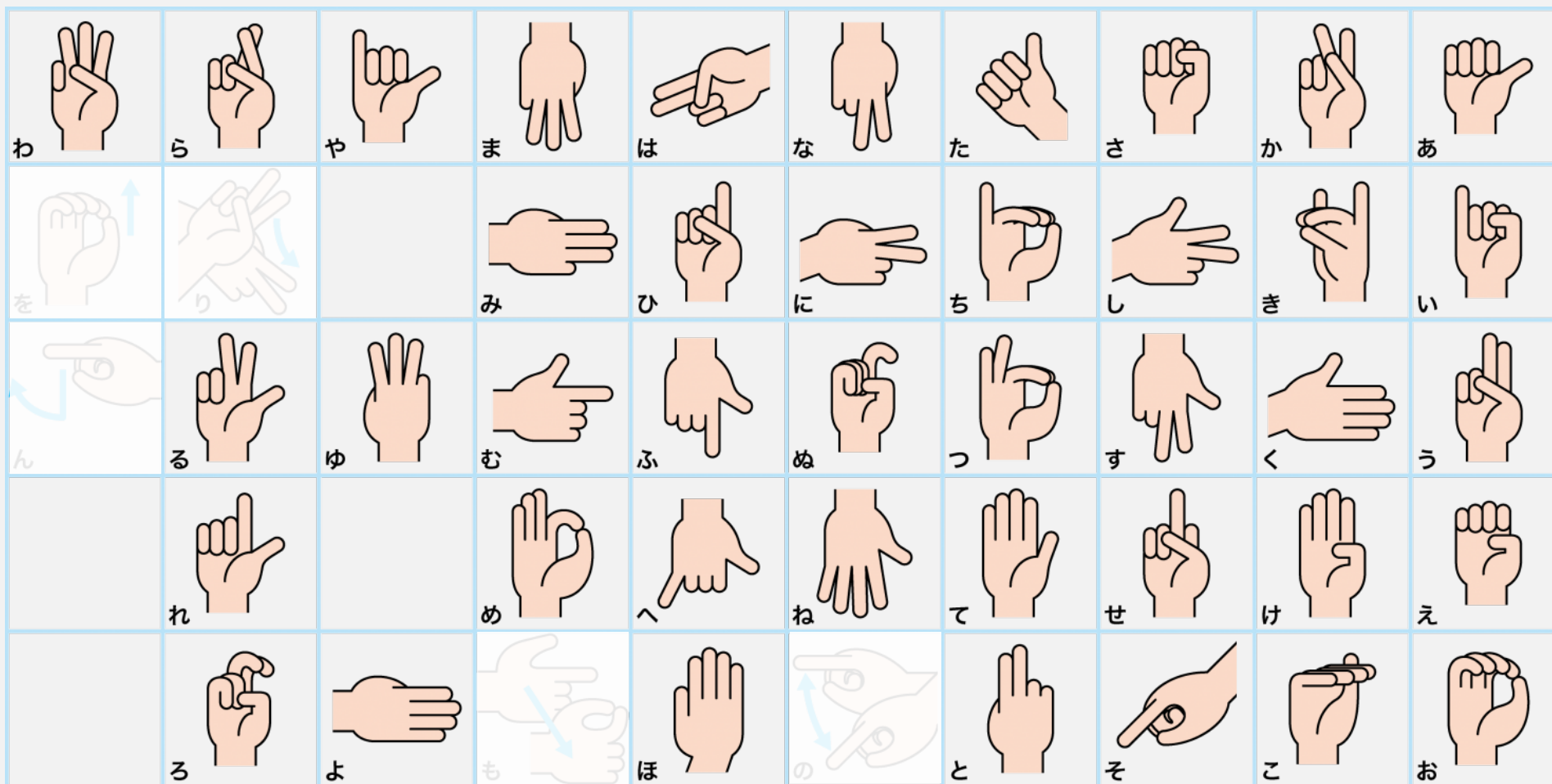
Background





# Japanese finger character

Background





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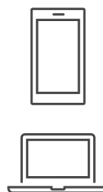


To construct a finger character recognition system

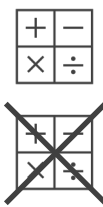
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with a small image data set



to use a generic device



with low computational cost



# Purpose of this work



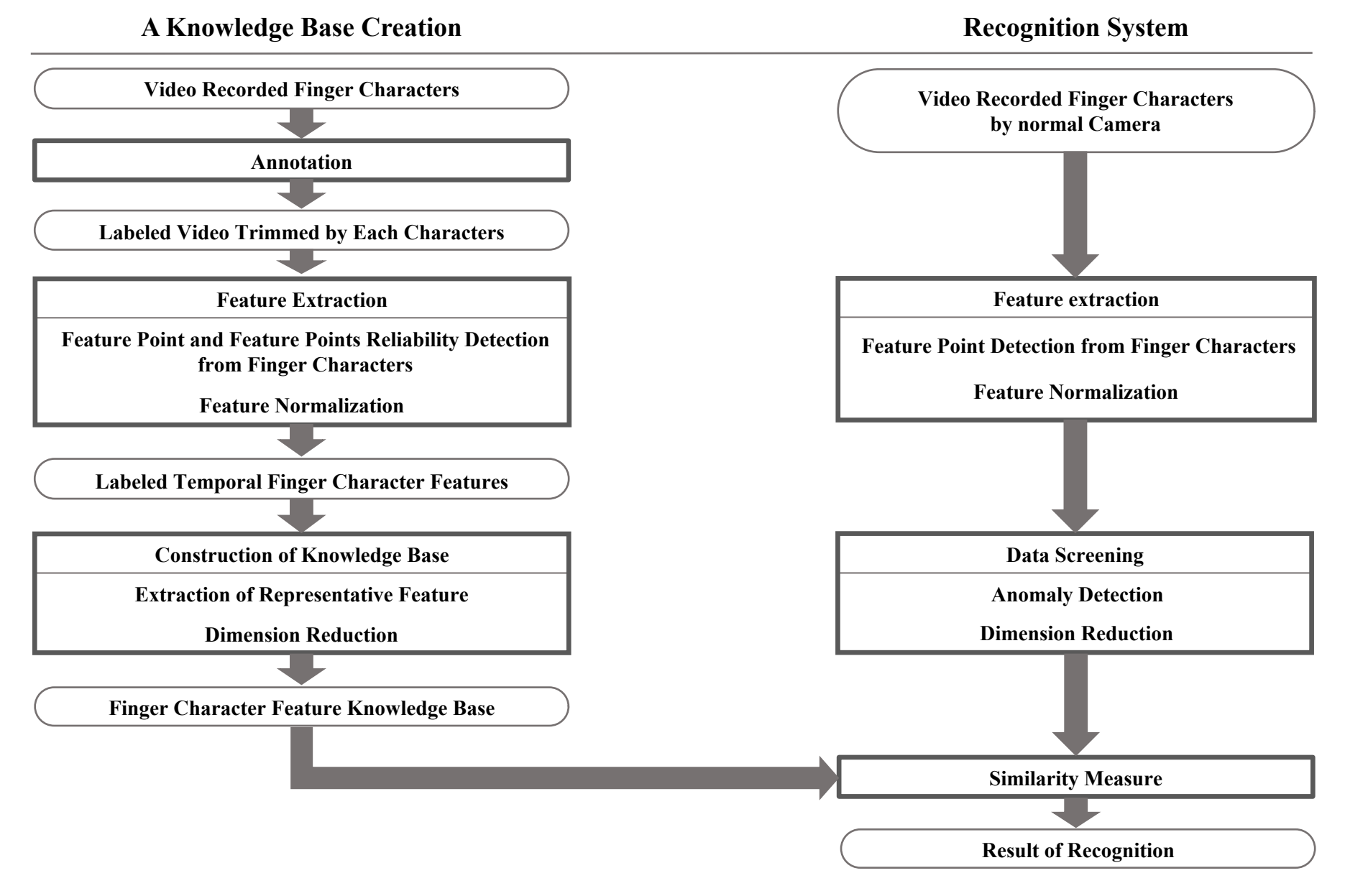
- We propose new knowledge base creation methods using the reliability of the finger joint coordinates.
- We evaluate the knowledge base creation method.
- We implement a finger character recognition system with higher recognition accuracy.



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# Overview of our recognition system





# A knowledge base creation system



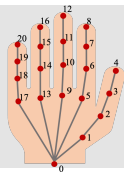
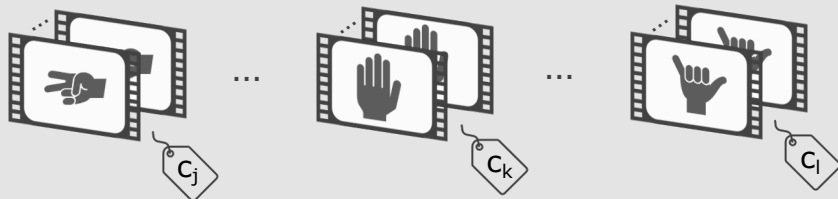
## A Knowledge Base Creation



Finger Character Video

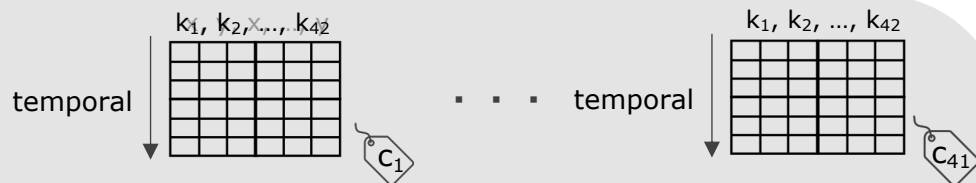


Annotation



Feature Extraction using OpenPose

Feature Normalization



Labeled Temporal Finger Character Features



Representative Feature  
Dimension Reduction

Knowledge Base

## Recognition System



Videos and images by normal camera



Feature Extraction using OpenPose

Feature Normalization



Data Screening

Anomaly Detection  
Dimension Reduction



Similarity Measure



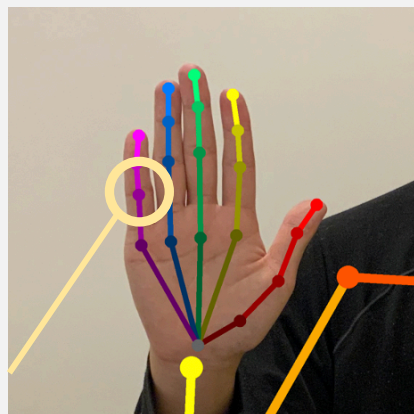
Result of Recognition



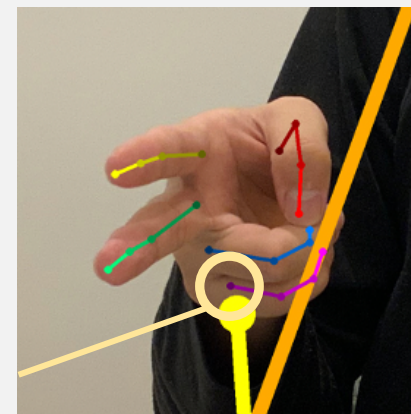
# Definition of the reliability of coordinates

The reliability is a value in the range 0~1 that shows accuracy of the coordinates obtained by OpenPose.

(x, y, 0.8946)



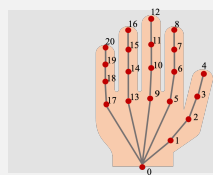
(x, y, 0.5881)



(X-coordinate, Y-coordinate, the reliability of the coordinates)



# Improvement point



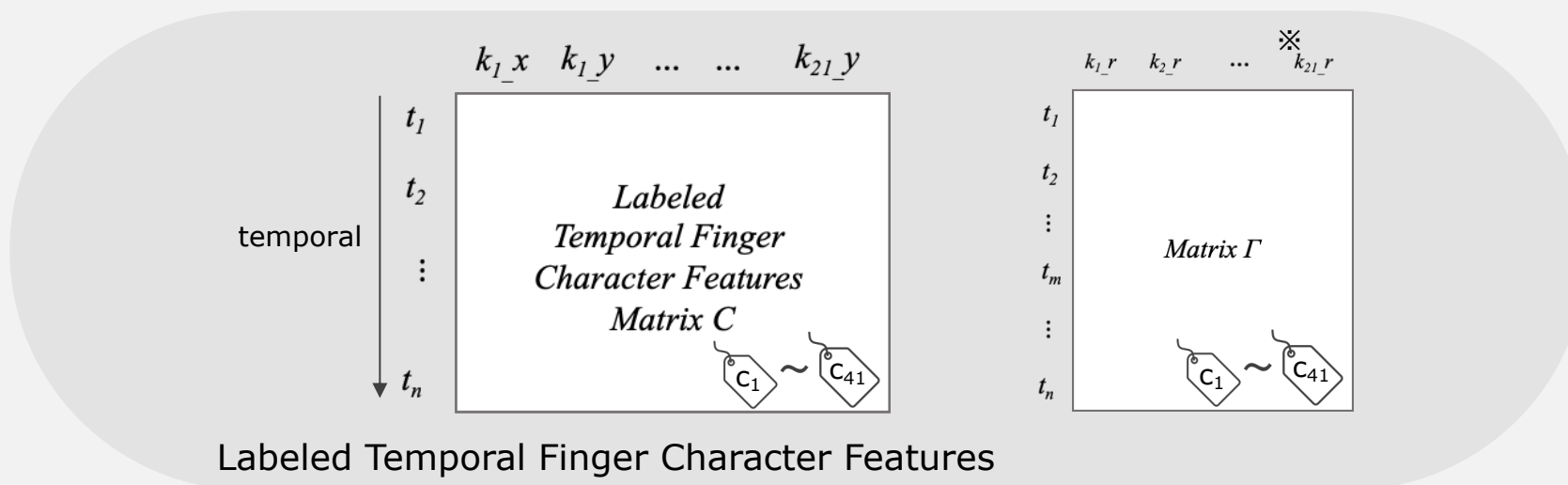
## Feature Extraction using OpenPose



Finger joint coordinates



the reliability of coordinates



## New Knowledge Base Creation Methods

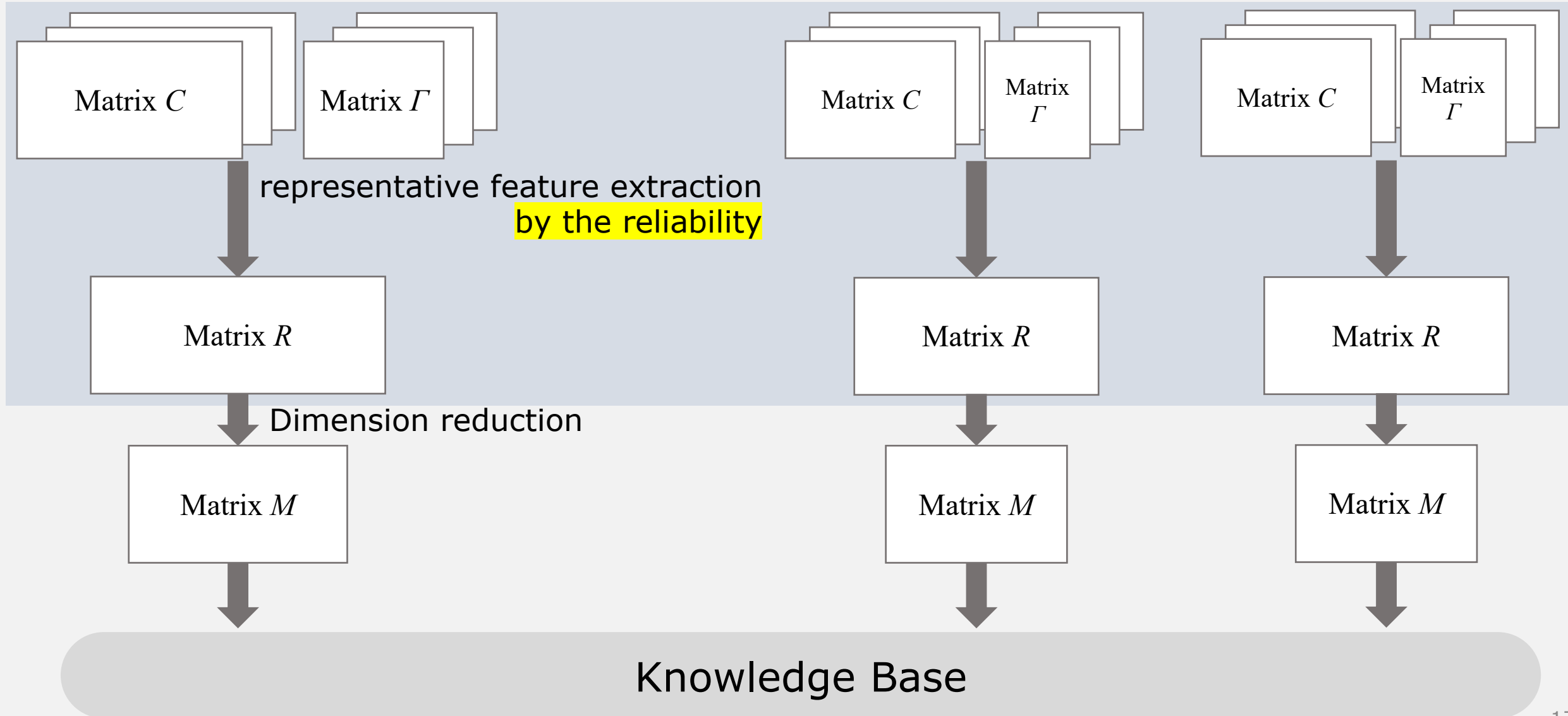
new knowledge base creation methods by reliability of coordinates



Knowledge Base

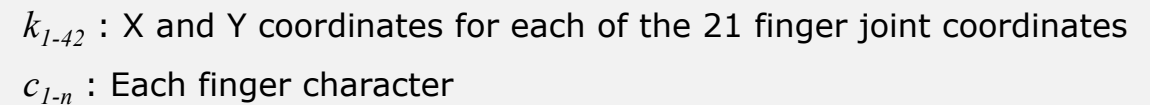


# Outline of new knowledge base creation methods by reliability





Proposed method





# Representative feature extraction

1

Creation by **the highest average value**

2

Creation by **the highest minimum value**

3

Creation by **the average of averages**

4

Creation by **the sum of the maximum and minimum values**



# ① Creation by the highest average value

For each frame, calculate the average of the reliability.

Find the highest average value.

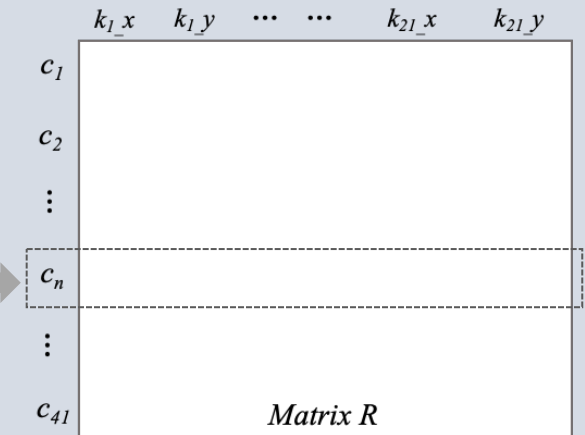
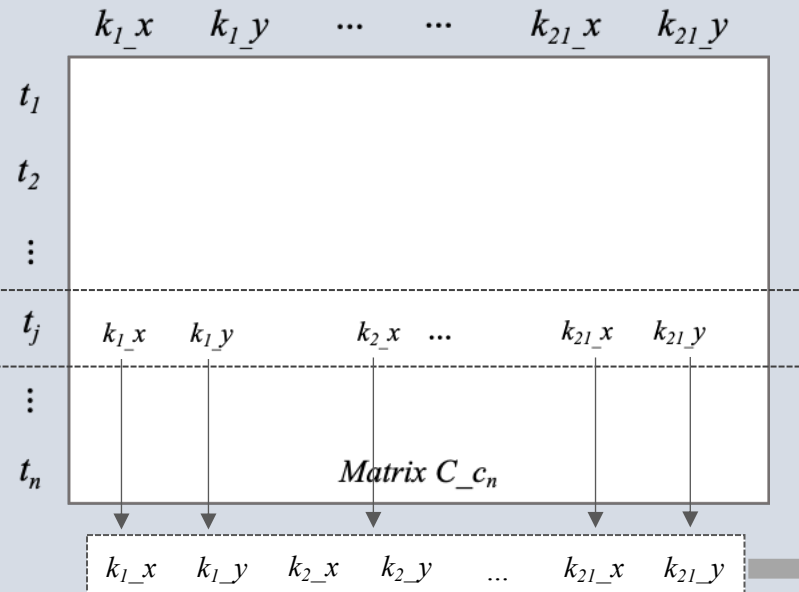
	$k_{1\_r}$	$k_{2\_r}$	...	$k_{21\_r}$	
$t_1$	<i>Matrix <math>\Gamma_{c_n}</math></i>				$t_{1\_ave}$
$t_2$					$t_{2\_ave}$
$\vdots$					$\vdots$
$t_j$					$t_{j\_ave}$ max
$\vdots$					$\vdots$
$t_n$					$t_{n\_ave}$



Extract the coordinates of the frame with the highest average value.



Store the extracted representative values in the knowledge base





## ② Creation by the highest minimum value



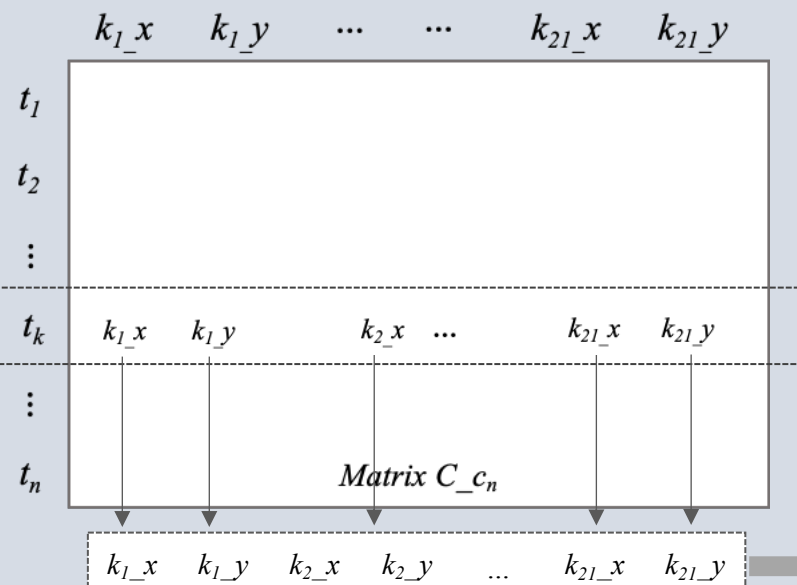
Proposed method

For each frame, extract the minimum value of the reliability.

Find the highest minimum value.

	$k_{1\_r}$	$k_{2\_r}$	...	$k_{21\_r}$	
$t_1$					$t_{1\_min}$
$t_2$					$t_{2\_min}$
$\vdots$					$\vdots$
$t_k$	<i>Matrix <math>\Gamma_{c_n}</math></i>				$t_{k\_min}$ max
$t_n$					$t_{n\_min}$

Extract the coordinates of the frame with the highest minimum value.



Store the extracted representative values in the knowledge base

	$k_{1\_x}$	$k_{1\_y}$	...	$k_{21\_x}$	$k_{21\_y}$
$c_1$					
$c_2$					
$\vdots$					
$c_n$					
$\vdots$					
$c_{41}$					

Matrix  $R$



### ③ Creation by the average of averages



Proposed method

For each frame, calculate the average of the reliability.

Calculate the average value of all averages (= A)

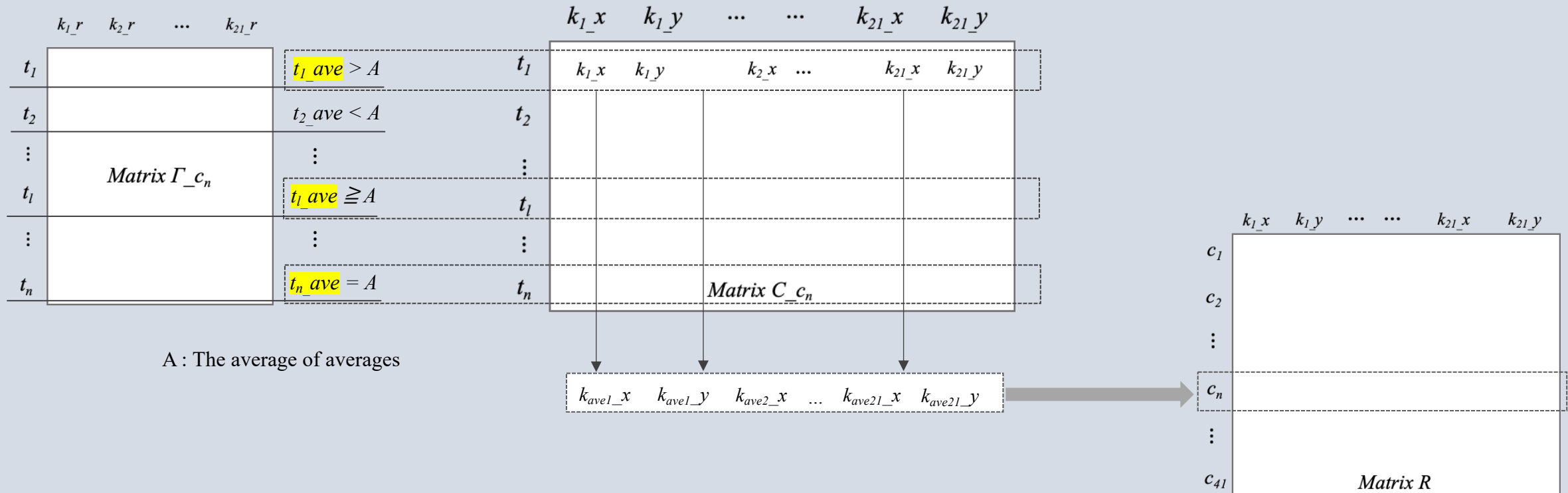


Calculate the average for the same coordinates of all extracted frames.



Store the extracted representative values in the knowledge base

Find all averages higher than A.





# ④ Creation by the sum of the maximum and minimum values

For each frame, extract the maximum and minimum values of the reliability.

Sum the maximum and minimum values.

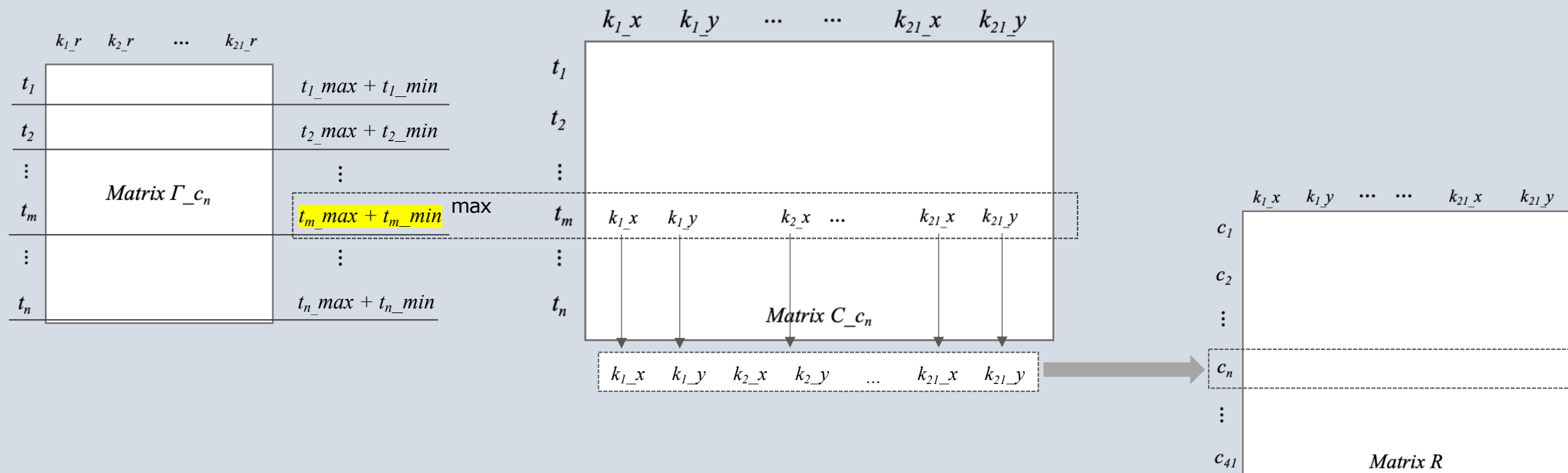


Extract the coordinates of the extracted frame.



Store the extracted representative values in the knowledge base

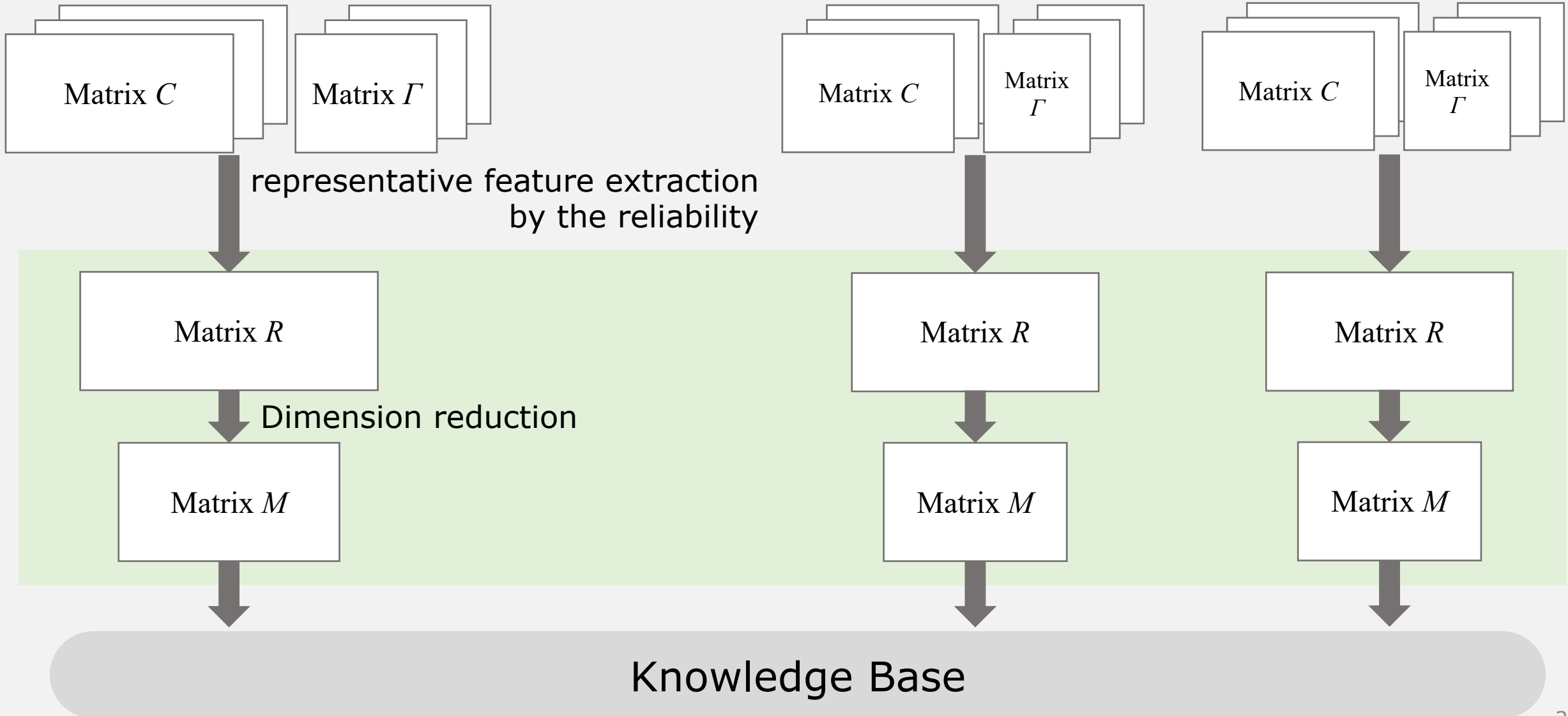
Find the highest value of the sum.





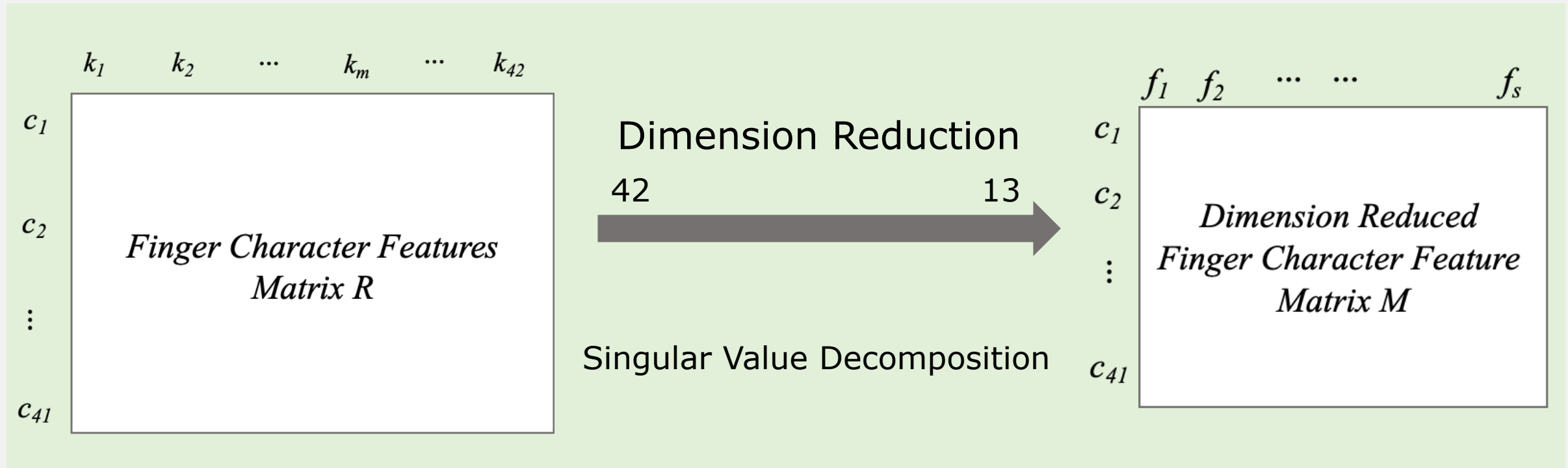
# Outline of new knowledge base creation methods by reliability

● ● ● ● ●  
Proposed method





# Dimension reduction



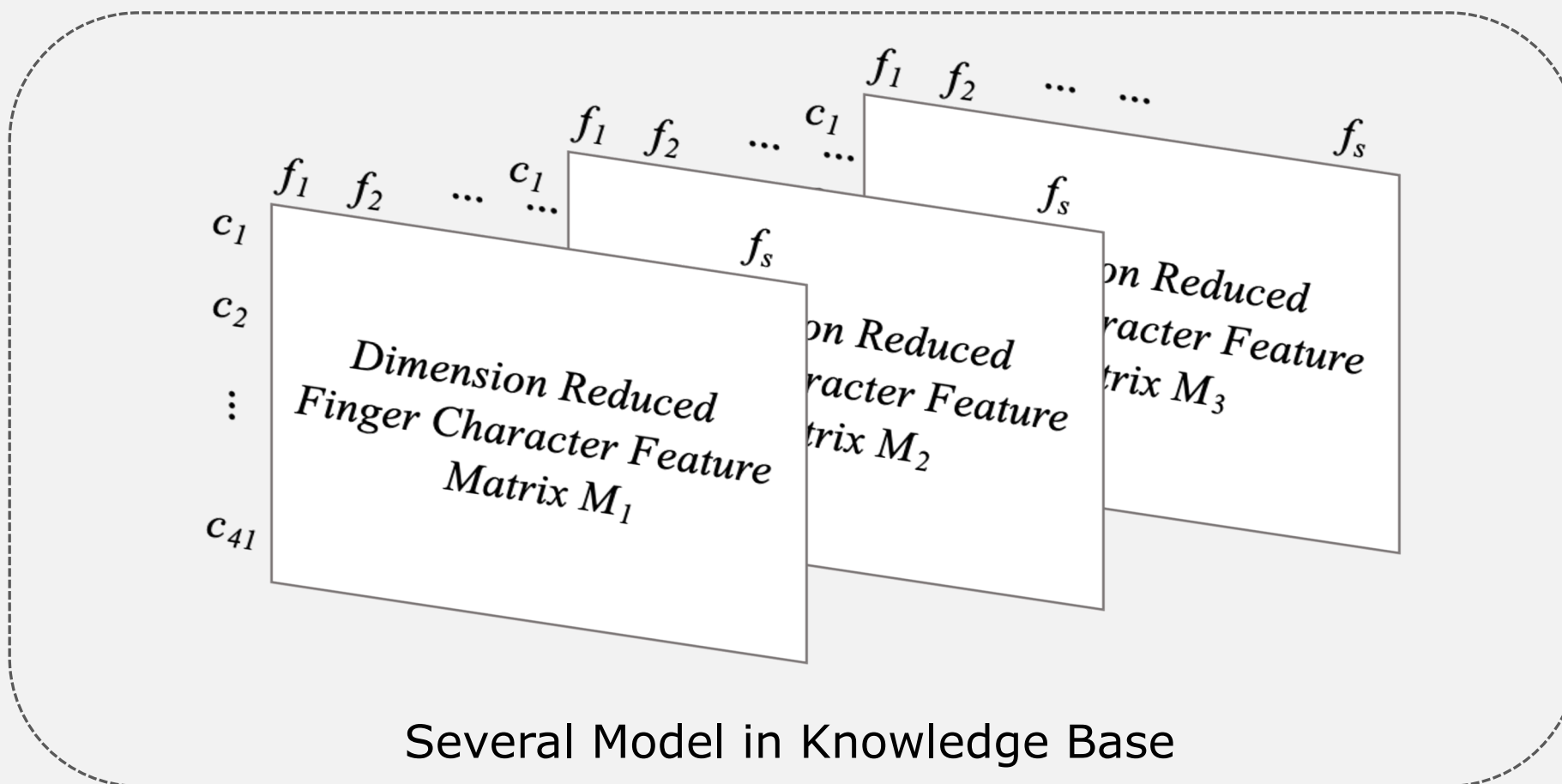
$k_{1-42}$  : X and Y coordinates for each of the 21 finger joint coordinates

$c_{1-n}$  : Each finger character

$f_{1-s}$  : The dimension reduced finger character features



# The knowledge base



$c_{1-n}$  : Each finger character

$f_{1-s}$  : The dimension reduced finger character features



# Recognition system

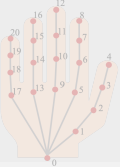
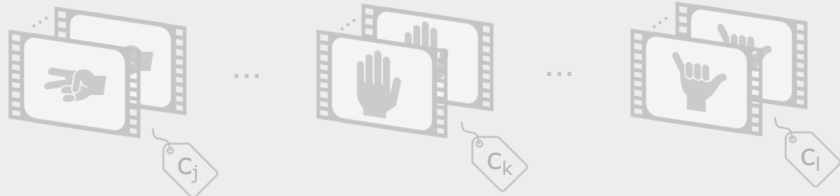
## A Knowledge Base Creation



Finger Character Video



Annotation



Feature Extraction using OpenPose

Feature Normalization



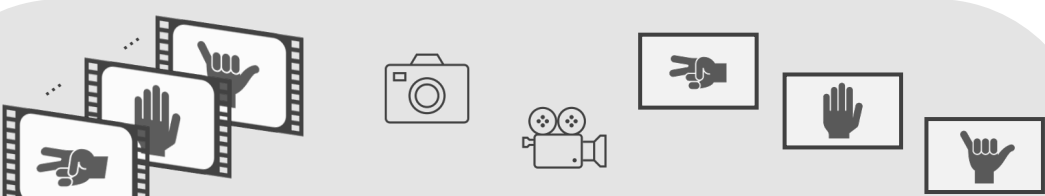
Labeled Temporal Finger Character Features



Representative Feature  
Dimension Reduction

Knowledge Base

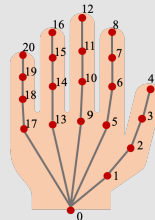
## Recognition System



Videos and images by normal camera



Feature Extraction using OpenPose



Feature Normalization



Data Screening

Anomaly Detection  
Dimension Reduction



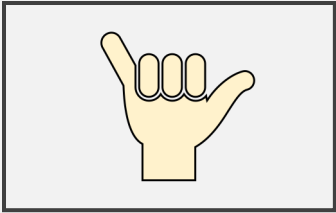
Similarity Measure



Result of Recognition



# Similarity measure



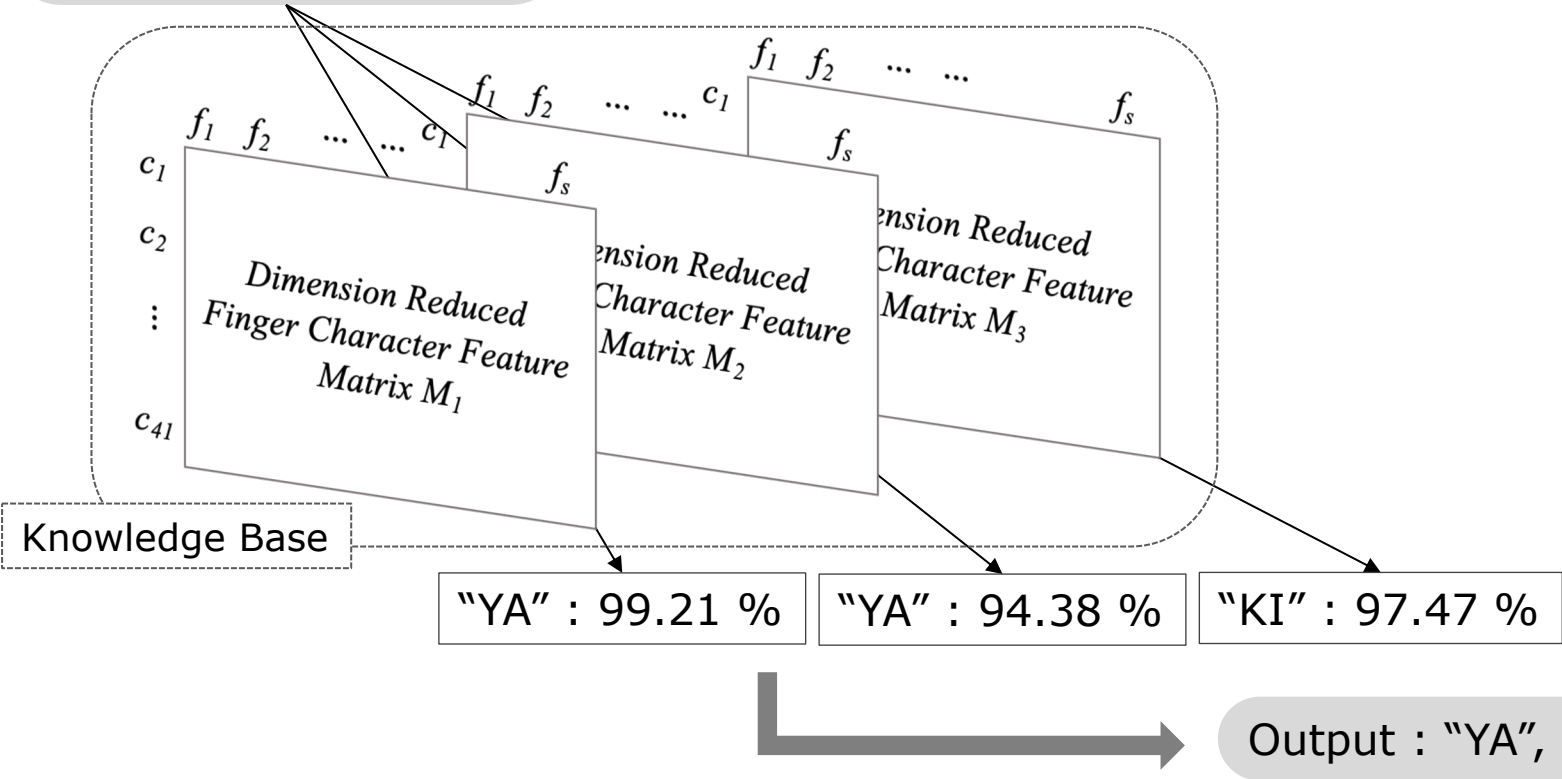
Extraction features

$k_1, k_2, \dots, k_m, \dots, k_{42}$

Dimension Reduction

$f_1, f_2, \dots, f_s$  input data

Similarity Measure



$k_{1-42}$  : X and Y coordinates for each of the 21 finger joint coordinates

$f_{1-s}$  : The dimension reduced finger character features



# Outline



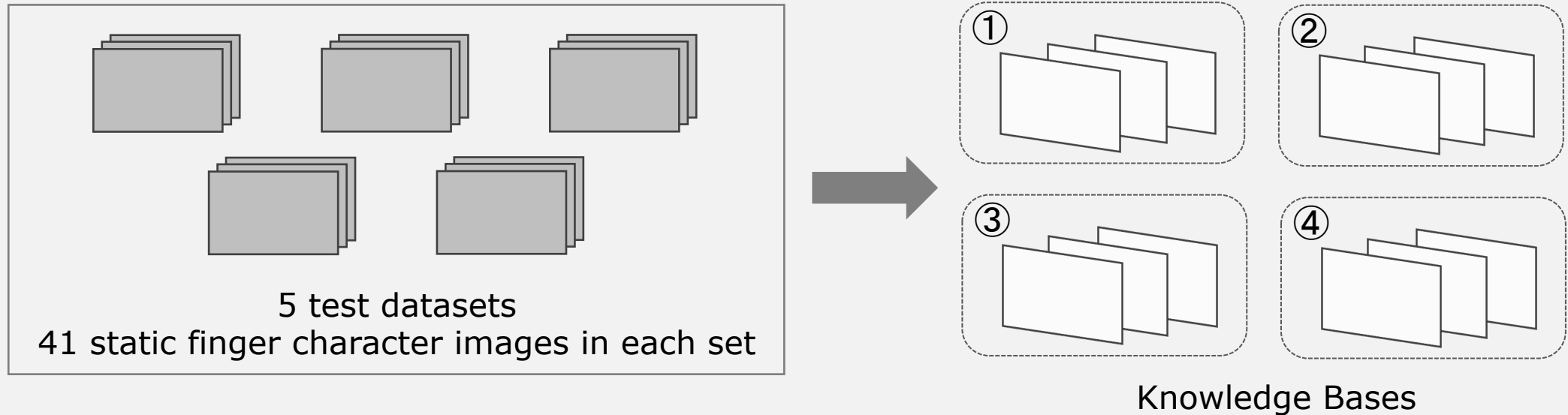
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## Experiment

Verify accuracy using test data and knowledge base.



## Evaluation

Evaluate and compare with recognition accuracy of previous work.



# Experiment result

Perform recognition on each knowledge base and each of the five test data sets.  
Calculate the accuracy for each test data set.

Types of Knowledge base	Person-1	Person-2	Person-3	Person-4	Person-5	average
① Highest-Ave	87.50 %	63.41 %	60.98 %	68.75 %	62.50 %	68.63 %
② Highest-Min	82.50 %	63.41 %	60.98 %	65.63 %	62.50 %	67.00 %
③ Average-Ave	85.00 %	68.29 %	58.54 %	71.86 %	60.00 %	68.74 %
④ Sum-of-Max-Min	82.50 %	63.41 %	58.54 %	68.75 %	60.00 %	66.64 %

previous work	Person-1	Person-2	Person-3	Person-4	Person-5	average
accuracy	87.50 %	63.41 %	60.98 %	75.00 %	62.50 %	69.88 %

Person-n : The data consists 41 static finger characters in each set.



Results of our previous work and the results of the third approach (Average-Ave) that had the highest accuracy in this work.

	Person-1	Person-2	Person-3	Person-4	Person-5	Average
Previous work	87.50 %	63.41 %	60.98 %	75.00 %	62.50 %	69.88 %
③ Average-Ave	85.00 %	68.29 %	58.54 %	71.86 %	60.00 %	68.74 %

About 5%

Positive case

About 3%

Negative case



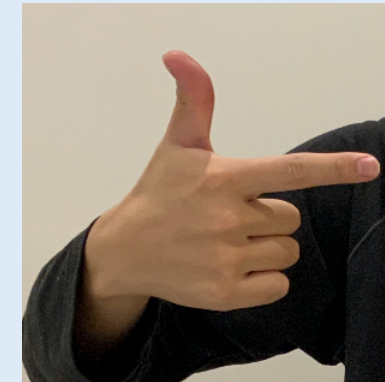
# Example of positive cases

previous work



KE

previous work



MU



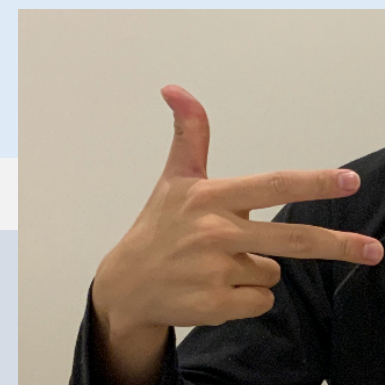
E



③ Average-Ave



E



SHI



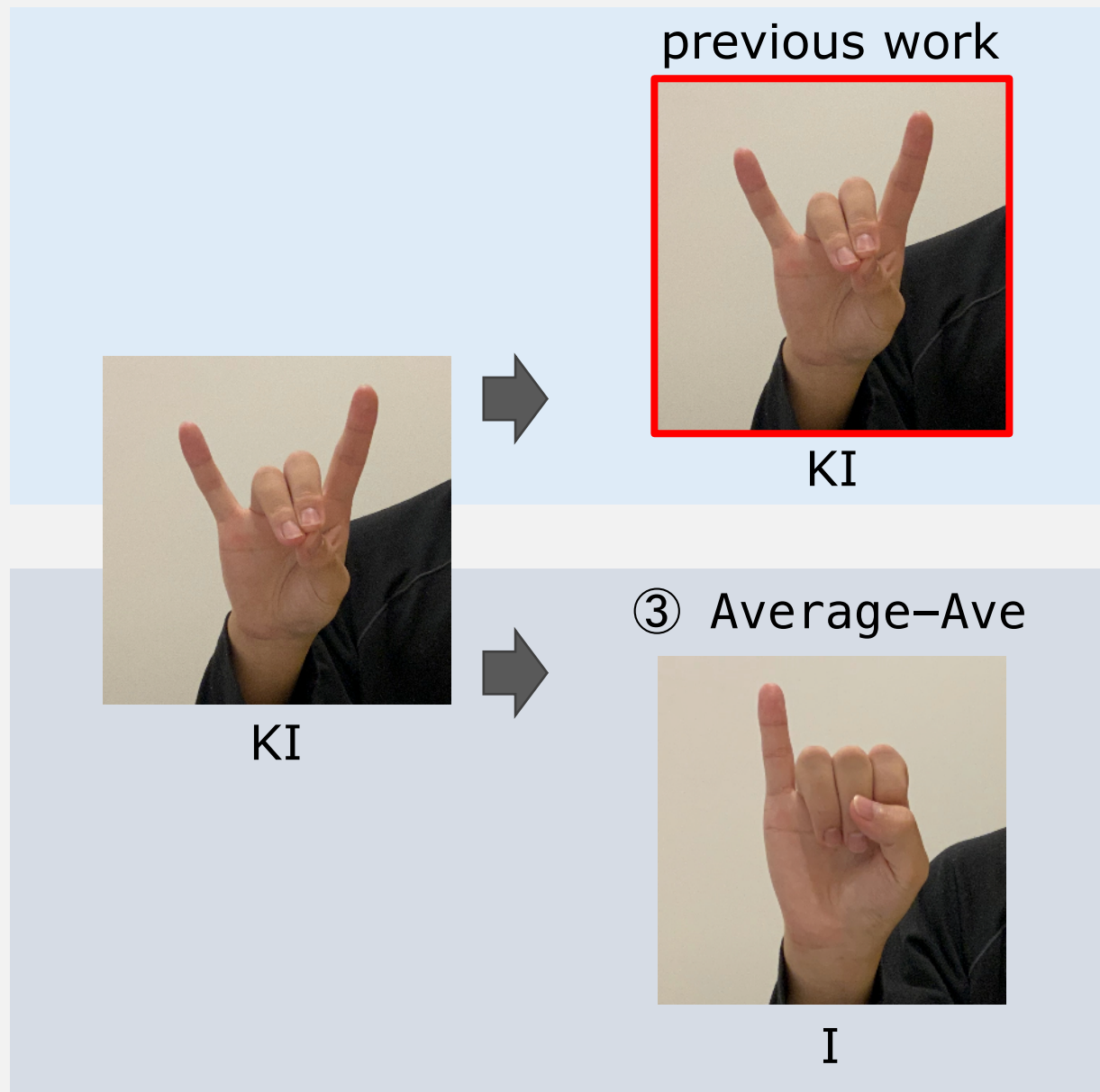
③ Average-Ave



SHI






# Example of a negative case





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-  We proposed a new knowledge base creation method using the reliability of coordinates detected from finger character videos for recognition.
-  Our method enables the creation of a knowledge base and metadata with high accuracy from a small amount of training data.
-  Our method achieves the same level of accuracy when comparing to our previous work in the finger character recognition using the knowledge base created in our method.



I

To improve the accuracy of the recognition

II

To develop the recognition of dynamic finger characters and sign language that has various motions

III

To develop an application